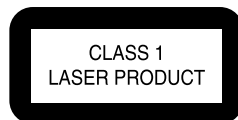


Service Service Service



Service Manual



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DVD+ReWritable Page

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1. Technical Specifications and Connection Facilities

1.1 VAD8031 functionality:

- Loading of 8 cm and 12 cm discs by a motorized tray
- Disc type recognition and in case of a DVD+RW disc laser power calibration
- Servo control for disc rotation, sledge movements, tilt, focus and actuator position
- EFM+ encoding / decoding for DVD, and EFM decoding for CD
- Writes and read DVD+RW discs and reads DVD, CD and CD-R/RW discs
- Linking control, header insertion and sector number updating at record
- Interfacing to the MPEG back-end for control and for data
- The back-end has to provide MPEG data processing, data buffering, construction of logical format for Lead-in, Data area and Lead-out part of the DVD+RW disc

1.2 Connections

The following interfaces are provided for connecting the drive to the MPEG back-end Application:

- Power Connector: 4-pin supply interface
- IDE Connector: 40-pin command and data transfer interface

IDE Bus selection:

- Jumper Selection: 6-pin IDE Bus selector

Attention: Jumper has to be in position "Master"

1.3 Read and Write Speeds

| Type of Disc (Function) | Disc Rotation Speed |
|-------------------------|---------------------|
| Read Speed CD | CAV 7x |
| Read Speed DVD | CAV 4x |
| Write Speed DVD+RW | ZCAV 2.4x |
| Write Speed DVD+R | ZCAV 2.4x |

2. Safety Instructions, Warnings and Notes

2.1 Safety Instructions

2.1.1 General Safety

Safety regulations require that during a repair:

- Connect the unit to the mains via an isolation transformer.
- Replace safety components, indicated by the symbol ▲, only by components identical to the original ones. Any other component substitution (other than original type) may increase risk of fire or electrical shock hazard.

Safety regulations require that after a repair, you must return the unit in its original condition. Pay, in particular, attention to the following points:

- Route the wires/cables correctly, and fix them with the mounted cable clamps.
- Check the insulation of the mains lead for external damage.
- Check the electrical DC resistance between the mains plug and the secondary side:
 1. Unplug the mains cord, and connect a wire between the two pins of the mains plug.
 2. Set the mains switch to the 'on' position (keep the mains cord unplugged!).
 3. Measure the resistance value between the mains plug and the front panel, controls, and chassis bottom.
 4. Repair or correct unit when the resistance measurement is less than 1 MΩ.
 5. Verify this, before you return the unit to the customer/user (ref. UL-standard no. 1492).
 6. Switch the unit 'off', and remove the wire between the two pins of the mains plug.

2.1.2 Laser Safety

This unit employs a laser. Only qualified service personnel may remove the cover, or attempt to service this device (due to possible eye injury).

Laser Device Unit

| | |
|-----------------|--|
| Type | : Semiconductor laser GaAlAs |
| Wavelength | : 650 nm (DVD) : 780 nm (VCD/CD) |
| Output Power | : 20 mW (DVD+RW writing) : 0.8 mW (DVD reading) : 0.3 mW (VCD/CD reading) |
| Beam divergence | : 60 degree |

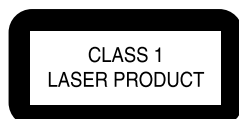


Figure 2-1 Class 1 Laser Product

Note: Use of controls or adjustments or performance of procedure other than those specified herein, may result in hazardous radiation exposure. Avoid direct exposure to beam.

2.2 Warnings

2.2.1 General

- All ICs and many other semiconductors are susceptible to electrostatic discharges (ESD, symbol ▲). Careless handling during repair can reduce life drastically. Make sure that, during repair, you are at the same potential as the mass of the set by a wristband with resistance. Keep components and tools at this same potential. Available ESD protection equipment:
 - Complete kit ESD3 (small tablemat, wristband, connection box, extension cable and earth cable) 4822 310 10671.
 - Wristband tester 4822 344 13999.
- Be careful during measurements in the live voltage section. The primary side of the power supply (pos. 1005), including the heatsink, carries live mains voltage when you connect the player to the mains (even when the player is 'off!'). It is possible to touch copper tracks and/or components in this unshielded primary area, when you service the player. Service personnel must take precautions to prevent touching this area or components in this area. A 'lightning stroke' and a stripe-marked printing on the printed wiring board, indicate the primary side of the power supply.
- Never replace modules, or components, while the unit is 'on'.

2.2.2 Laser

- The use of optical instruments with this product, will increase eye hazard.
- Only qualified service personnel may remove the cover or attempt to service this device, due to possible eye injury.
- Repair handling should take place as much as possible with a disc loaded inside the player.
- Text below is placed inside the unit, on the laser cover shield:

CAUTION VISIBLE AND INVISIBLE LASER RADIATION WHEN OPEN AVOID EXPOSURE TO BEAM
 ADVARSEL SYNLIG OG USYNLIG LASERSTRÅLING VED ÅBNING UNDGÅ UDSÆTTELSE FOR STRÅLING
 ADVARSEL SYNLIG OG USYNLIG LASERSTRÅLING NÅR DEKSEL ÅPNES UNNGÅ EKSPONERING FOR STRÅLEN
 VARNING SYNLIG OCH OSYNLIG LASERSTRÅLING NÅR DENNA DEL ÅR ÖPPNAD BETRÄKTA EJ STRÅLEN
 VARO! AVATT AESSA OLET ALTTIINA NÄKYVÄLLE JA NÄKYMÄTTÖMÄLLE LASER SÄTEILYLLE. ÄLÄ KATSO SÄTEESEEN
 VORSICHT SICHTBARE UND UNSICHTBARE LASERSTRÄHLUNG WENN ABDECKUNG GEÖFFNET NICHT DEM STRAHL AUSSETZEN
 DANGER VISIBLE AND INVISIBLE LASER RADIATION WHEN OPEN AVOID DIRECT EXPOSURE TO BEAM
 ATTENTION RAYONNEMENT LASER VISIBLE ET INVISIBLE EN CAS D'OUVERTURE EXPOSITION DANGEREUSE AU FAISCEAU

Figure 2-2 Warning text

3. Directions For Use

Not applicable

4. Mechanical Instructions

Note that exploded views can be found in chapter 10

4.1 General

Follow the dismantling instructions in described order.
Do not place the unit with its PWB on a hard surface (e.g. table), as it could damage the components on it.
Always place something soft (a towel or foam cushion) under it.
Never touch the lens of the OPU.
Take sufficient ESD measures during handling.

4.2 Dismantling

You can divide the Basic Engine into the following parts:

1. Loader (frame and tray, clamp)
2. PWB (or 'mono board')
3. DVD-Module (OPU, turntable motor, and sledge-motor assy)
4. Encasing

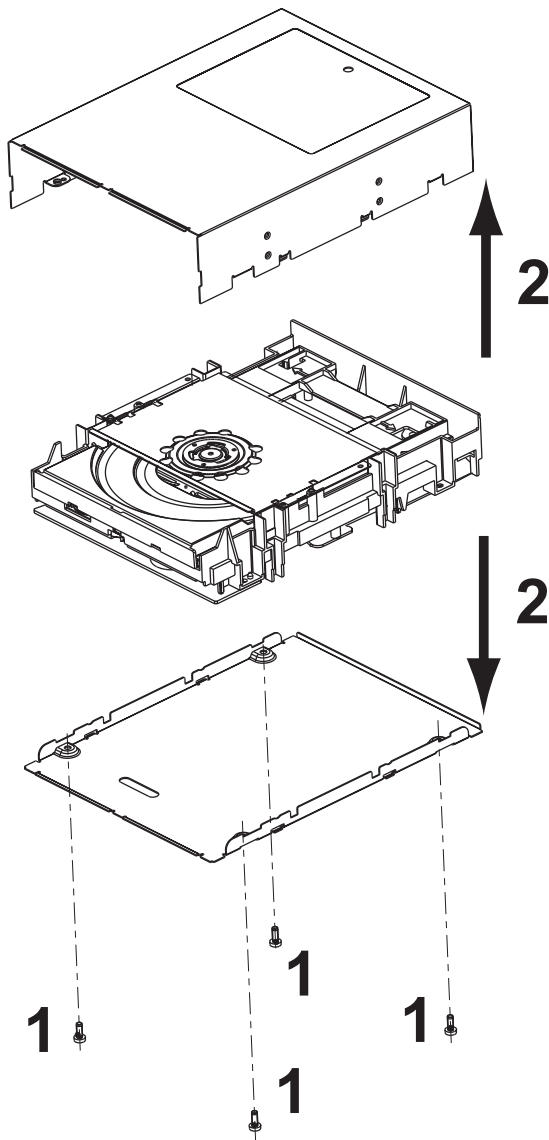


Figure 4-1 Basic Engine dismantling (part1)

4.3 Cabinet and Clamper Bridge

- Remove the encasing by releasing the four screws [1], see figure 4-1
- Make sure that you do not lose the 5 heat paths (gray rubber pieces that conduct the heat from the ICs to the case)!
- Remove the clamper bridge assy, by releasing the two screws [1], see figure 4-2

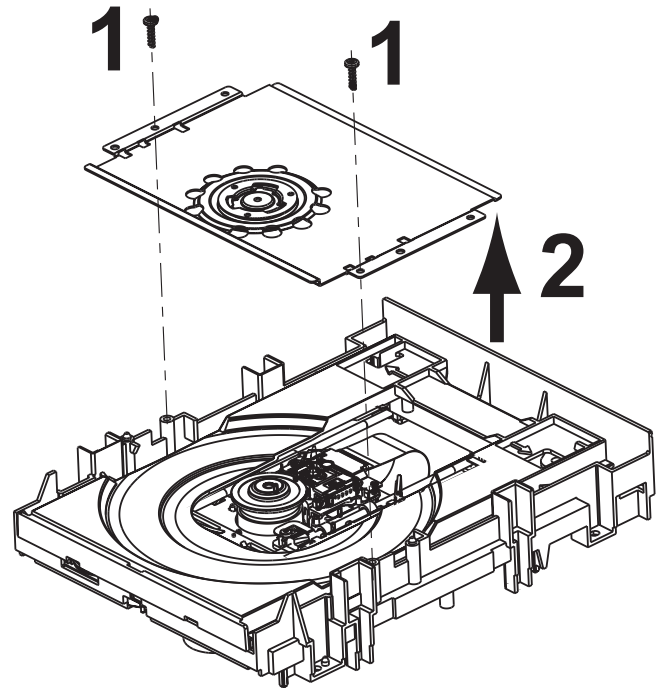


Figure 4-2 Remove Clamper Bridge

4.4 Tray

- Remove encasing as described in 4.3
- Disengage the two holders that fix the tray [1], see figure 4-3, and pull out the tray [2]

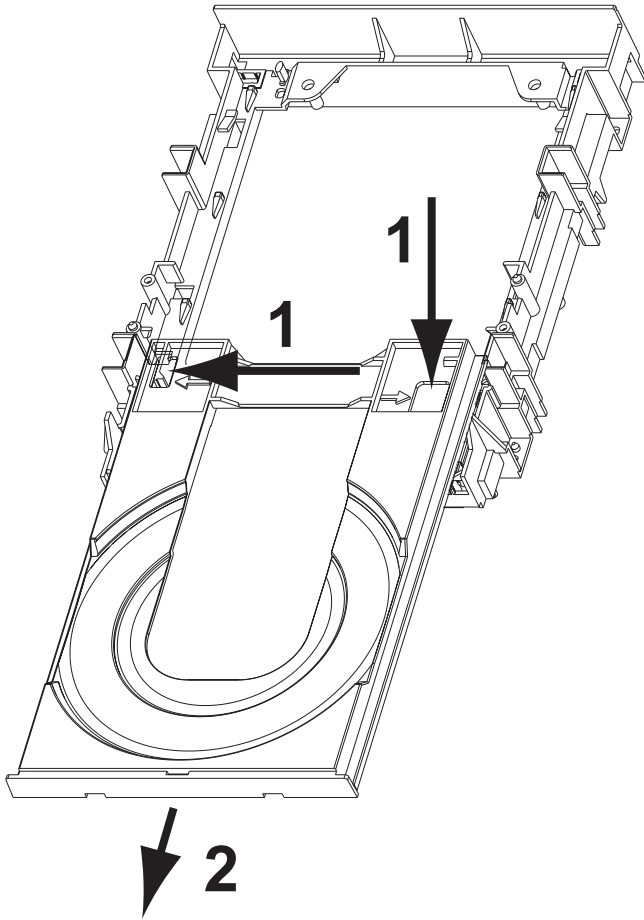


Figure 4-3 Remove Tray

4.5 Printed Board

Note: After Exchanging the PWB (or the DVD-M) the complete drive has to be adjusted! Refer to chapter 8 for adjustment instructions!

- Remove encasing and clamper bridge as described in 4.3
- Disconnect the four flex foils from the PWB connectors
- Remove the 2 screws that hold the PWB, see figure 4-4
- At assembly make sure that the 5 heat paths (gray rubber pieces) are placed on the ICs!

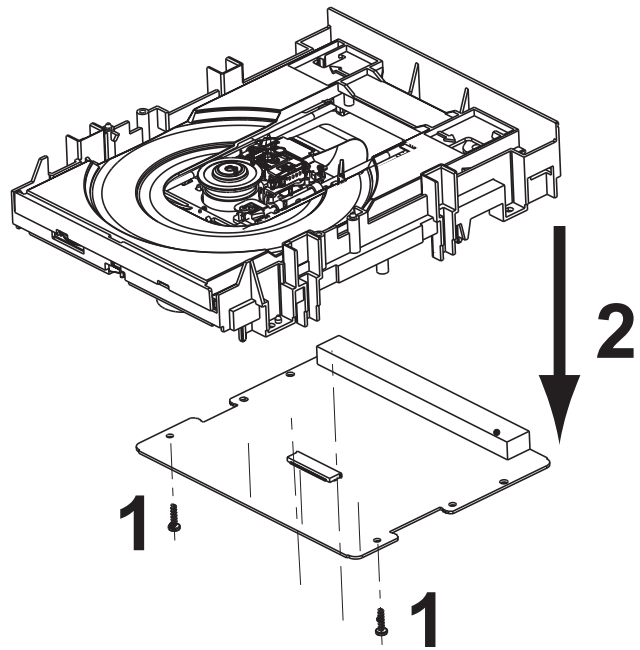


Figure 4-4 Remove PWB

4.6 DVD-M

Caution: Never try to align or repair the DVD-Module itself! Only the factory can do this properly. Service engineers are only allowed to exchange the sledge motor assy. After Exchanging the DVD-M (or the PWB) the complete drive has to be adjusted! Refer to chapter 8 for adjustment instructions!

- Remove encasing, clamper bridge and PWB as described in 4-3 and 4-5
- Remove the four screws [1], see figure 4-5.
- Now you can remove the DVDM

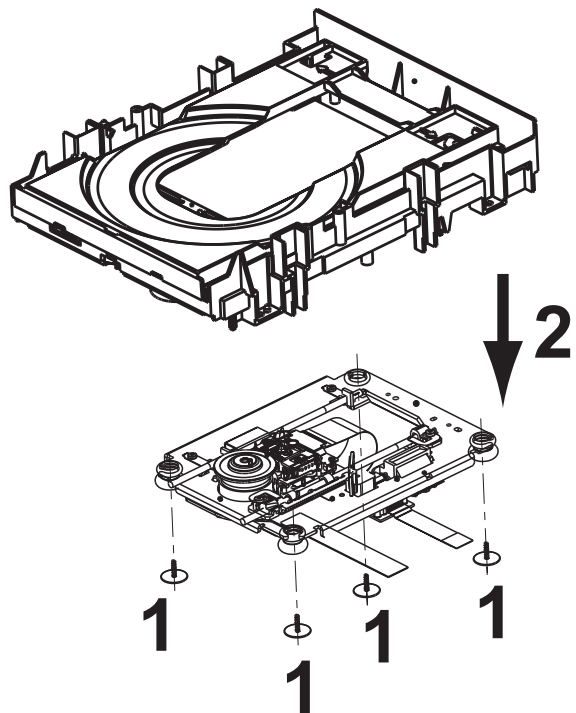


Figure 4-5 Remove DVDM

4.7 Sledge Motor Assembly

Caution: Never try to align or repair the DVD-Module itself!
Only the factory can do this properly. Service engineers are only allowed to exchange the sledge motor assy.

- Place the DVD-Module, with the laser facing downwards on a soft surface.
- Remove the three screws that hold the sledge-motor assy and lift the assy upwards. You can replace it now.

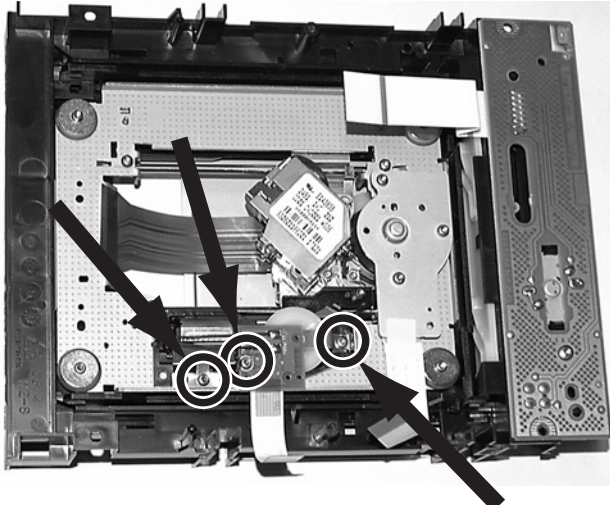


Figure 4-6 Remove Sledge Motor Assy

4.8 Re-assembly

To re-assemble the module, do all processes in reverse order.
Take care of the following:

- **Sledge-motor assy:** Mesh the teeth of the sledge motor and sledge rack properly, during mounting of the sledge motor assy.
- **Heat Paths:** Put the 5 heat paths (gray rubber pieces) back to their position on the ICs, see figure 4-7.
- **Complete module:** Place all wires/cables in their original positions
- **Emergency opening slot:** Be sure that the slot for the emergency tray opener is covered by adhesive tape!
- **Jumper selection:** Jumper has to be in position "Master"!



Figure 4-7 Heat Paths

5. Diagnostic Software

5.1 General

Please refer to the service manual of the recorder for a description of the complete Diagnostics Software. In this manual only drive specific error codes are explained.

5.2 Error Codes

With DSW command 910 (Digital Board Chrysalis) the set software can retrieve an overview of all occurred engine errors.

```

D&S - HyperTerminal
File Edit View Call Transfer Help
[Icons]
DS:> 910
Momentary errors (0-9): 0x21 0x00 0x00 0x20 0x00 0x00 0x00 0x00 0x00 0x00
Cumulative errors (1-9): 0x00 0x80 0x20 0x00 0x00 0x00 0x00 0x00 0x00
Software fatal assert : 256 cpowermanager.cpp
091000:
Test OK @
DS:>_

```

5.2.1 Momentary Errors

Byte 0: latest error:

Overview of the BE error codes.

| error code | error | meaning |
|------------|--------------------------|---|
| 0x00 | no_error | No error has occurred |
| 0x01 | illegal_command_error | Command not allowed in this state or unknown command |
| 0x02 | illegal_parameter_error | Parameter(s) not valid for this command |
| 0x03 | command_timeout_error | The maximum execution time for the command has exceeded |
| 0x04 | sledge_home_error | The sledge could not be moved home |
| 0x05 | sledge_calibration_error | An error occurred during calibration of the sledge |
| 0x06 | sledge_unstable_error | The sledge detected unstable control |
| 0x07 | speed_timeout_error | Spindle motor could not reach its target speed within timeout |
| 0x08 | speed_window_error | Measured spinning speed is not within expected window |
| 0x09 | focus_timeout_error | Focus could not be achieved within the timeout |
| 0x0A | focus_retries_error | The amount of focus retries expired |
| 0x0B | focus_agc_error | The focus agc results are out of range |
| 0x0C | radial_timeout_error | Servo didn't get on track within the timeout |
| 0x0D | radial_retries_error | Servo didn't get on track after several retries |
| 0x0E | radial_agc_error | The radial agc results are out of range |
| 0x0F | radial_init_error | Unreliable signal scaling after the radial initialisation |
| 0x10 | hf_pll_error | HF-decoder pll could not lock to HF signal |

| | | |
|------|-----------------------------------|---|
| 0x11 | wobble_pll_error | Wobble pll could not lock to wobble signal |
| 0x12 | subcode_timeout_error | Subcode information could not be read |
| 0x13 | subcode_notfound_error | Requested subcode item could not be found |
| 0x14 | header_timeout_error | Header information could not be read |
| 0x15 | adip_timeout_error | Adip information could not be read |
| 0x16 | adip_window_error | Adip address was not within expected window |
| 0x17 | adip_sync_error | No adip sync was detected |
| 0x18 | atip_timeout_error | Atip information could not be read |
| 0x19 | atip_notfound_error | Requested atip item could not be found |
| 0x1A | atip_window_error | Atip address was not within expected window |
| 0x1B | atip_sync_error | No atip sync was detected |
| 0x1C | tray_error | Tray could not be closed or opened within the timeout |
| 0x1D | seek_error | The requested seek couldn't be performed within the timeout |
| 0x1E | no_hf_present_error | Attempt to read from a blank area |
| 0x1F | record_error | An error occurred during the recording |
| 0x20 | illegal_stopaddress_error | The requested stopaddress with modify-stop-address is not valid |
| 0x21 | no_disc_error | No disc is detected |
| 0x22 | not_initialised_error | The system is not initialised (e.g. seek on unknown disc-type) |
| 0x23 | illegal_medium_error | BE detected an unsupported medium during disc recognition |
| 0x24 | cd_frequency_error | Measured HF frequency is not within CD frequency range |
| 0x25 | dvd_frequency_error | Measured HF frequency is not within DVD frequency range |
| 0x26 | re-served(non_existing_bca_error) | Attempt to read non-existing bca information |
| 0x27 | reserved(bca_read_error) | An error occurred during reading of bca information |
| 0x28 | selftest_error | An error occurred during the self-test of the BE |
| 0x29 | i2c_error | The I2C interface does not operate |
| 0x2A | laser_pll_error | Laser control pll did not lock or lost lock on write clock |
| 0x2B | laser_forward_sense_error | Forward sense value didn't change with changing laser power |
| 0x2C | jitter_optimisation_error | An error occurred during optimisation of the jitter |
| 0x2D | tilt_calibration_error | An error occurred during calibration of the tilt frame |
| 0x2E | reserved | |

| | | |
|------|----------------------------------|--|
| 0x2F | frontend_offset_calib_error | The offset in the frontend couldn't be calibrated |
| 0x30 | reserved | |
| 0x31 | wsg_calculation_error | An error occurred in the calculation of the write strategy |
| 0x32 | buffer_overflow_error | The buffer input stream overran the buffer output stream |
| 0x33 | return_value_invalid_error | The requested information is not available for this inquiry |
| 0x34 | illegal_recording_speed_error | The selected speed is not allowed for a recording on this medium |
| 0x35 | opc_media_parameter_error | The media parameters (info in ATIP/ADIP) are invalid or not read |
| 0x36 | opc_record_power_error | The final optimum power was not reached |
| 0x37 | opc_start_power_low_error | OPC start power too low (optimum power is higher) |
| 0x38 | opc_start_power_high_error | OPC start power too high (optimum power is lower) |
| 0x39 | opc_power_calculation_error | Error during OPC power calculation (samples are wrong) |
| 0x3A | opc_test_zone_full_error | OPC can't be performed because test zone is full |
| 0x3B | opc_bad_jitter_measurement_error | The jitter measurement during OPC samples readback failed |
| 0x3C | opc_read_samples_error | An error occurred during OPC readback sampling |
| 0x3D | ropc_alpha_overflow_error | The determined value for the optimum power is too high |
| 0x3E | ropc_alpha_ref_current_error | The alpha measurement reference current is wrong (IAN) |
| 0x3F | ropc_alpha_gain_error | The alpha measurement alpha gain is wrong |
| 0x40 | beta_over_under_flow_error | During the walking OPC a beta over-/under-flow was detected |
| 0x41 | not_enough_calib_points_error | Not enough valid calibration points available for re-calibration |
| 0x42 | not_enough_power_error | The calculated power during re-calibration exceeds max power |
| 0x43 | illegal_reading_speed_error | The selected speed is not allowed for the requested command |
| 0x44 | servo_fatal_error | The actuator dissipation became too high during a servo recovery |

This error is overwritten by the next player / inquiry command.

Byte 1 - 9: cumulative errors of previous error occurrences.
Every individual error has its own bit in the 9-byte structure as described in the drawing below:

Format of the BE error bytes

byte 1

| b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
|----------|-----------------|---------------------|---------------------|------------------|----------------------|----------------------|-------------------|
| reserved | FOCUS AGC ERROR | FOCUS RETRIES ERROR | FOCUS TIMEOUT ERROR | RADIAL AGC ERROR | RADIAL RETRIES ERROR | RADIAL TIMEOUT ERROR | RADIAL INIT ERROR |

byte 2

| | | | | | | | |
|------------|----------|---------------------------|-------------------|-----------------------|--------------------------|--------------------------------------|------------------------|
| TRAY ERROR | reserved | JITTER OPTIMIZATION ERROR | SLEDGE HOME ERROR | SLEDGE UNSTABLE ERROR | SLEDGE CALIBRATION ERROR | TILT SENSOR OFFSET CALIBRATION ERROR | TILT CALIBRATION ERROR |
|------------|----------|---------------------------|-------------------|-----------------------|--------------------------|--------------------------------------|------------------------|

byte 3

| | | | | | | | |
|--------------|------------|---------------|-----------------------|---------------------------|-------------------------|-----------------------|-----------------------|
| RECORD ERROR | SEEK ERROR | NO DISC ERROR | NOT INITIALIZED ERROR | ILLEGAL STOPADDRESS ERROR | ILLEGAL PARAMETER ERROR | ILLEGAL COMMAND ERROR | COMMAND TIMEOUT ERROR |
|--------------|------------|---------------|-----------------------|---------------------------|-------------------------|-----------------------|-----------------------|

byte 4

| | | | | | | | |
|-------------------|----------|----------|--------------|---------------------|----------------------|------------------------|-----------------------|
| SERVO FATAL ERROR | reserved | reserved | HF PLL ERROR | NO HF PRESENT ERROR | HEADER TIMEOUT ERROR | SUBCODE NOTFOUND ERROR | SUBCODE TIMEOUT ERROR |
|-------------------|----------|----------|--------------|---------------------|----------------------|------------------------|-----------------------|

byte5

| | | | | | | | |
|------------------|-----------------|-------------------|--------------------|---------------------|-----------------|-------------------|--------------------|
| WOBBLE PLL ERROR | ADIP SYNC ERROR | ADIP WINDOW ERROR | ADIP TIMEOUT ERROR | ATIP NOTFOUND ERROR | ATIP SYNC ERROR | ATIP WINDOW ERROR | ATIP TIMEOUT ERROR |
|------------------|-----------------|-------------------|--------------------|---------------------|-----------------|-------------------|--------------------|

byte6

| | | | | | | | |
|-----------------------|---------------------|--------------------|-------------------------------|--------------------|---------------------|------------------------|----------------|
| WSG CALCULATION ERROR | DVD FREQUENCY ERROR | CD FREQUENCY ERROR | ILLEGAL RECORDING SPEED ERROR | SPEED WINDOW ERROR | SPEED TIMEOUT ERROR | NON EXISTING BCA ERROR | BCA READ ERROR |
|-----------------------|---------------------|--------------------|-------------------------------|--------------------|---------------------|------------------------|----------------|

byte7

| | | | | | | | |
|---------------------------|-----------------------------|-----------------------------------|-----------------|-----------------------------|----------------------|-----------------|------------------------|
| LASER FORWARD SENSE ERROR | NVRAM CHECKSUM UPDATE ERROR | FRONTEND OFFSET CALIBRATION ERROR | LASER PLL ERROR | ILLEGAL READING SPEED ERROR | ILLEGAL MEDIUM ERROR | SELFTTEST ERROR | I ² C ERROR |
|---------------------------|-----------------------------|-----------------------------------|-----------------|-----------------------------|----------------------|-----------------|------------------------|

byte8

| | | | | | | | |
|------------------------|----------------------------------|--------------------------|-----------------------------|----------------------------|---------------------------|------------------------|---------------------------|
| OPC READ SAMPLES ERROR | OPC BAD JITTER MEASUREMENT ERROR | OPC TEST ZONE FULL ERROR | OPC POWER CALCULATION ERROR | OPC START POWER HIGH ERROR | OPC START POWER LOW ERROR | OPC RECORD POWER ERROR | OPC MEDIA PARAMETER ERROR |
|------------------------|----------------------------------|--------------------------|-----------------------------|----------------------------|---------------------------|------------------------|---------------------------|

byte9

| | | | | | | | |
|----------------------------|----------------------|----------------------------|-------------------------------|------------------------|-----------------------|------------------------------|---------------------------|
| RETURN VALUE INVALID ERROR | BUFFER OVERRUN ERROR | BETA OVER/UNDER FLOW ERROR | NOT ENOUGH CALIB POINTS ERROR | NOT ENOUGH POWER ERROR | ROPC ALPHA GAIN ERROR | ROPC ALPHA REF CURRENT ERROR | ROPC ALPHA OVERFLOW ERROR |
|----------------------------|----------------------|----------------------------|-------------------------------|------------------------|-----------------------|------------------------------|---------------------------|

These errors are kept in memory until a power down of the drive (e.g. when recorder goes to standby) or reset of the drive.

5.2.2 Cumulative errors

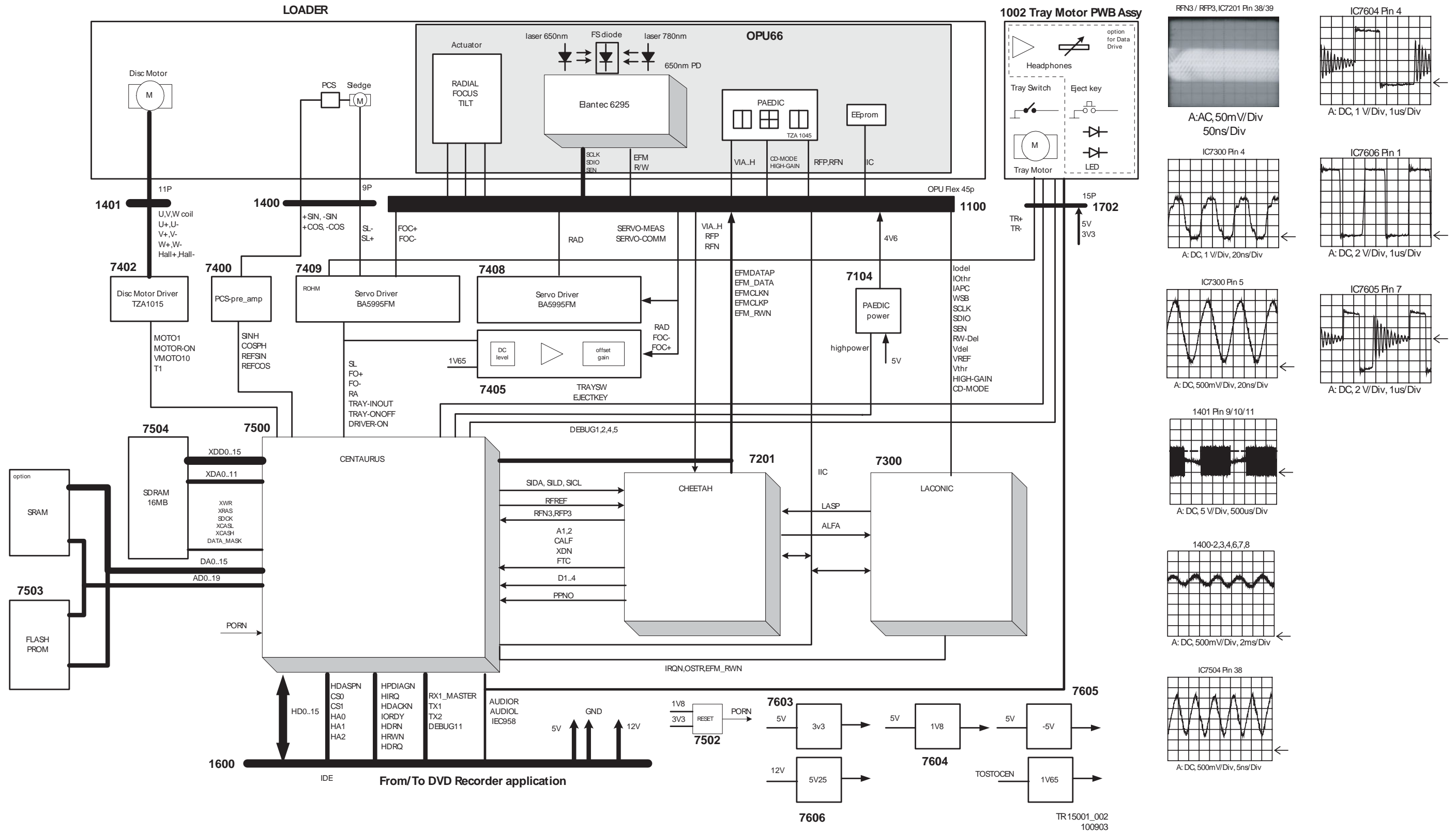
These errors are stored in EEPROM and are thus non-volatile showing the complete error history of the drive.
Byte 1 - 9: cumulative errors of previous player / inquiry error occurrences. These bytes are the same as the nine bytes (1-9) of the Momentary errors

5.2.3 Software fatal assert

Gives row number and file name in the source code of the firmware of the data path of the AV

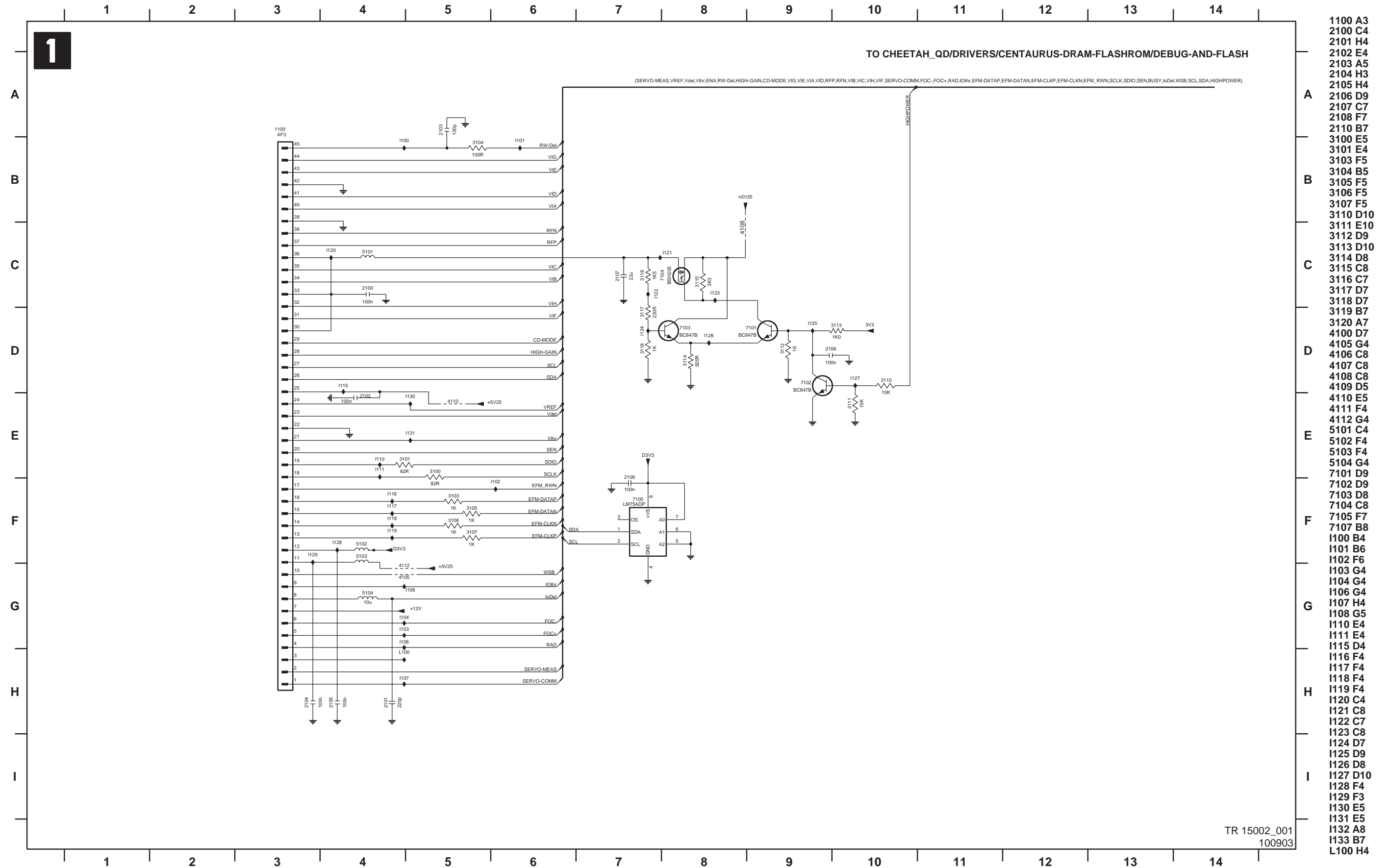
6. Block Diagram.

Block Diagram

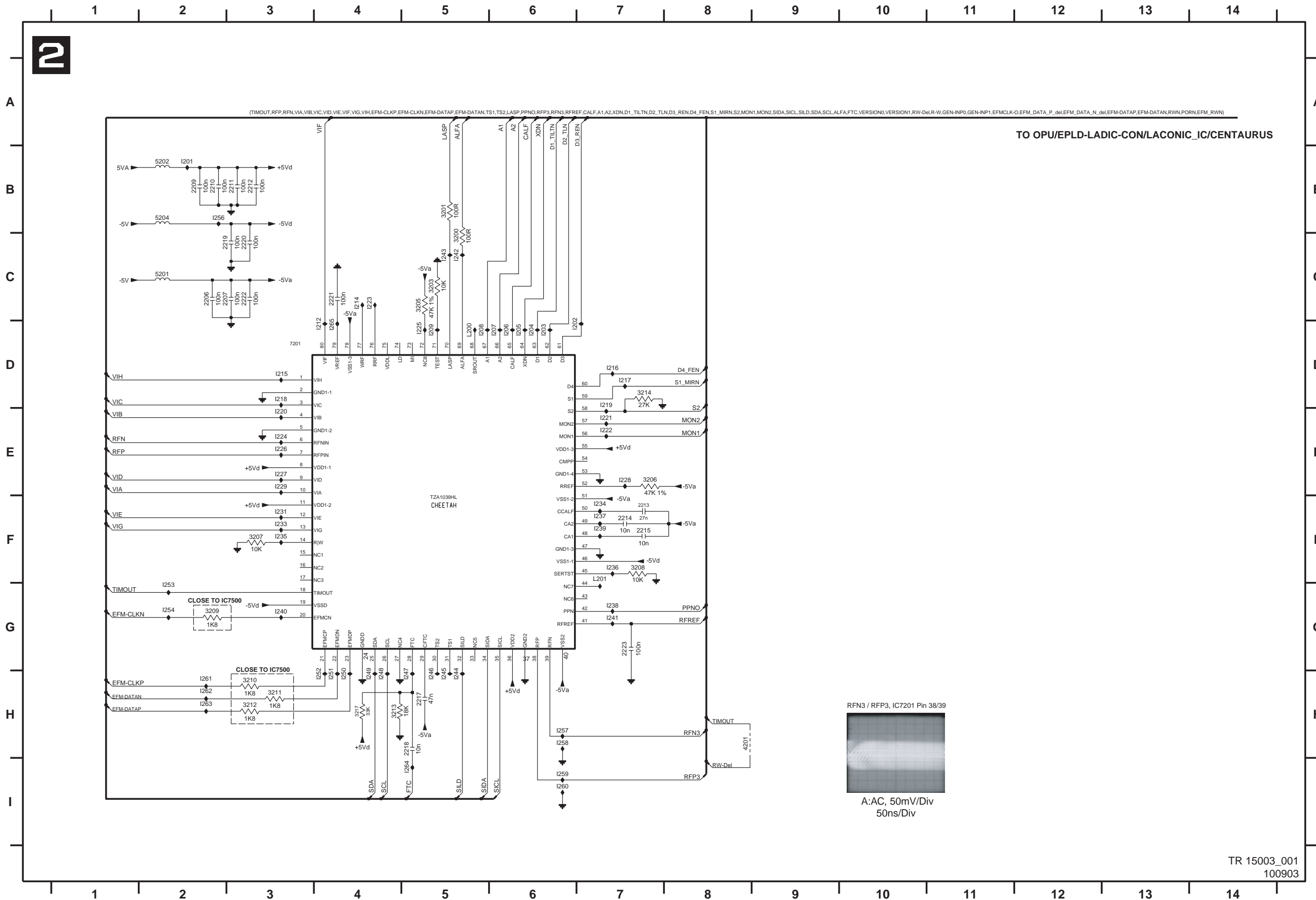


7. Electrical Diagrams and Print-Layouts

Servo Board: OPU Interface

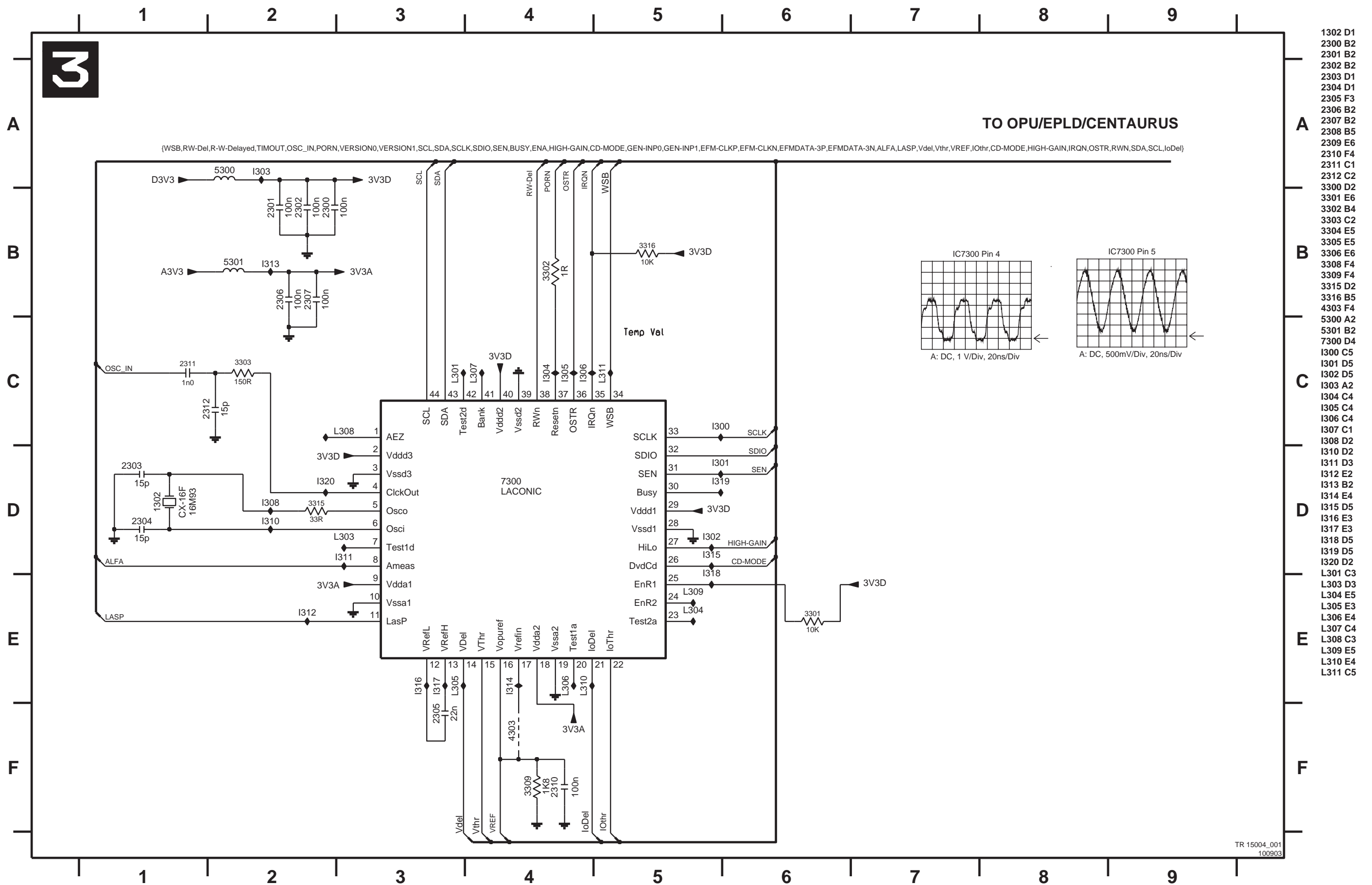


Servo Board: Cheetah



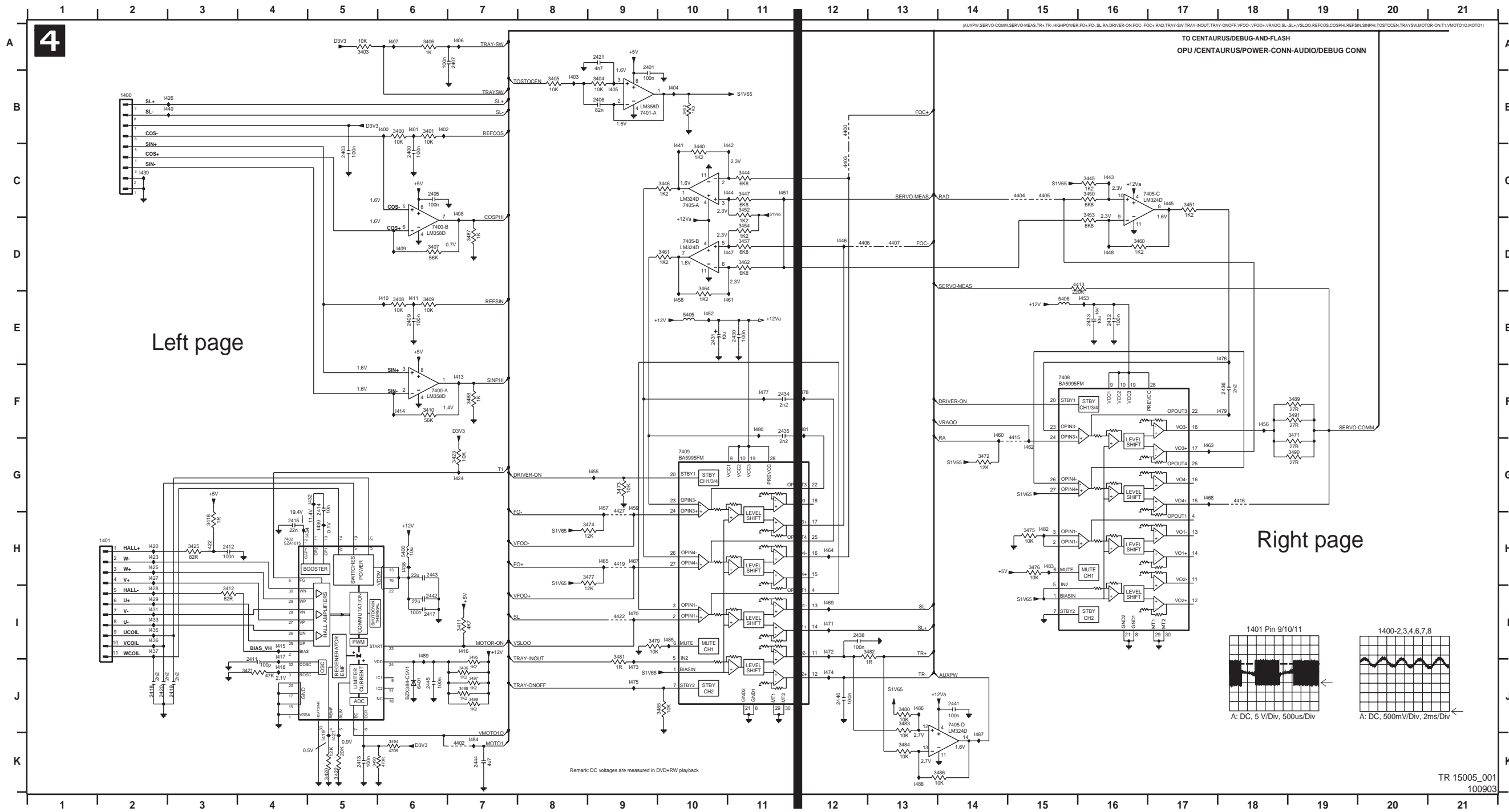
- 2204 B5
- 2205 B5
- 2206 C2
- 2207 C3
- 2209 B2
- 2210 B2
- 2211 B3
- 2212 B3
- 2213 F7
- 2214 F7
- 2215 F7
- 2217 H5
- 2218 H5
- 2219 C3
- 2220 C3
- 2221 C4
- 2222 C3
- 2223 G7
- 3200 C5
- 3201 B5
- 3202 C4
- 3203 C5
- 3204 C4
- 3205 C5
- 3206 E7
- 3207 F3
- 3208 F7
- 3209 G2
- 3210 H3
- 3211 H3
- 3212 H3
- 3213 H4
- 3214 D7
- 3215 D3
- 3216 D3
- 3217 H4
- 4200 H9
- 4201 H8
- 5201 C2
- 5202 B2
- 5204 B2
- 7201 D3
- I201 B2
- I202 D6
- I203 D6
- I204 D6
- I205 D6
- I206 D6
- I207 D6
- I208 D5
- I209 D5
- I210 D3
- I211 D4
- I212 D4
- I213 D3
- I214 C4
- I215 D3
- I216 D7
- I217 D7
- I218 D3
- I219 D7
- I220 E3
- I221 E7
- I222 E7
- I223 C4
- I224 E3
- I225 D5
- I226 E3
- I227 E3
- I228 E7
- I229 E3
- I230 F3
- I231 F3
- I232 F3
- I233 F3
- I234 F7
- I235 F3
- I236 F7
- I237 F7
- I238 G7
- I239 F7
- I240 G3
- I241 G7
- I242 C5
- I243 C5
- I244 H5
- I245 H5
- I246 H5
- I247 H5
- I248 H4
- I249 H4
- I250 H4
- I251 H4
- I252 H4
- I253 G2
- I254 G2
- I255 B2
- I256 B2
- I257 H6
- I258 H6
- I259 I6
- I260 I6
- I261 H2
- I262 H2
- I263 H2
- I264 I5
- I265 D4
- L200 D5
- L201 F7

Servo Board: Laconic

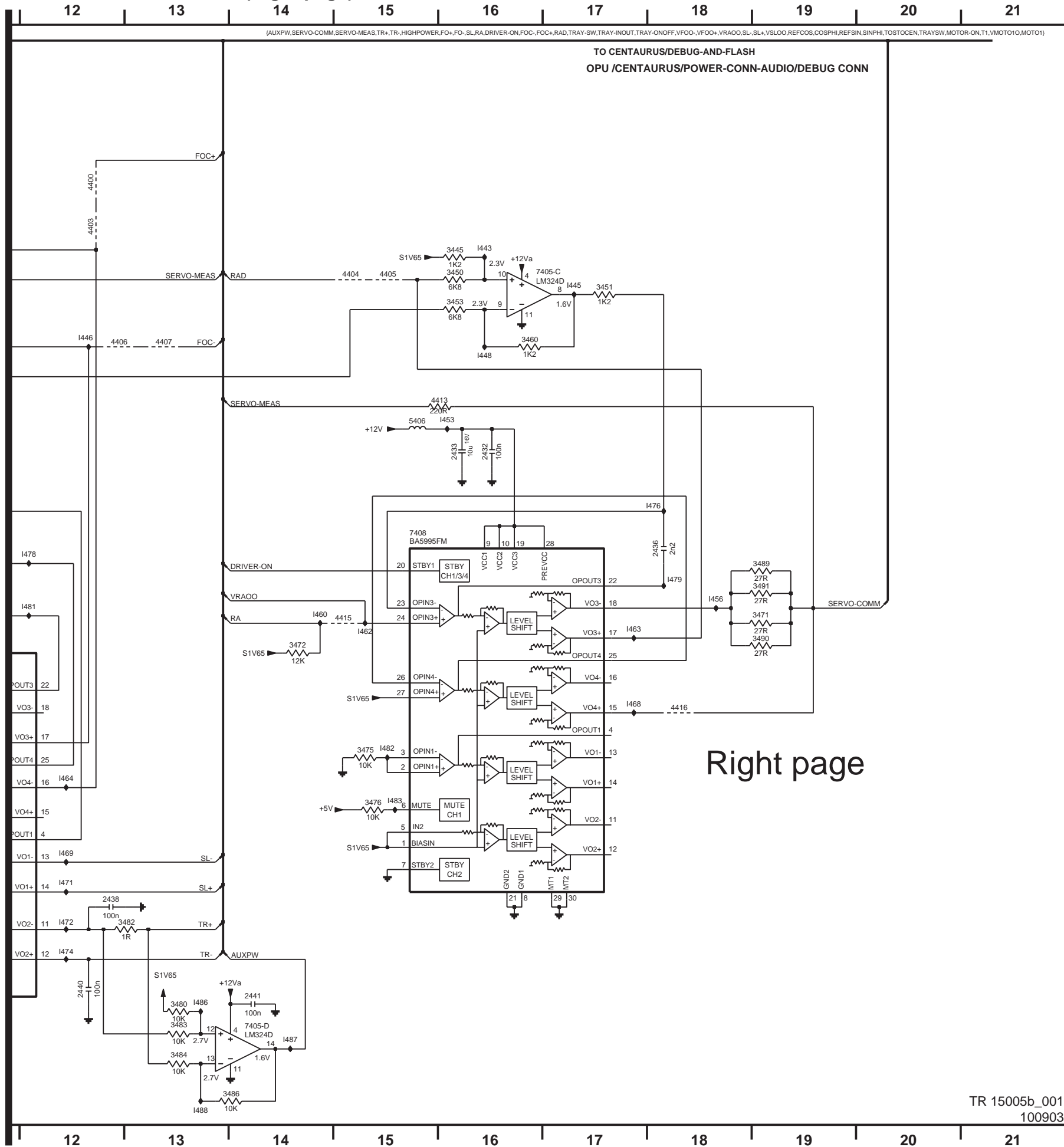


- 1302 D1
- 2300 B2
- 2301 B2
- 2302 B2
- 2303 D1
- 2304 D1
- 2305 F3
- 2306 B2
- 2307 B2
- 2308 B5
- 2309 E6
- 2310 F4
- 2311 C1
- 2312 C2
- 3300 D2
- 3301 E6
- 3302 B4
- 3303 C2
- 3304 E5
- 3305 E5
- 3306 E6
- 3308 F4
- 3309 F4
- 3315 D2
- 3316 B5
- 4303 F4
- 5300 A2
- 5301 B2
- 7300 D4
- I300 C5
- I301 D5
- I302 D5
- I303 A2
- I304 C4
- I305 C4
- I306 C4
- I307 C1
- I308 D2
- I310 D2
- I311 D3
- I312 E2
- I313 B2
- I314 E4
- I315 D5
- I316 E3
- I317 E3
- I318 D5
- I319 D5
- I320 D2
- L301 C3
- L303 D3
- L304 E5
- L305 E3
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- L307 C4
- L308 C3
- L309 E5
- L310 E4
- L311 C5

Servo Board: Drivers (Overview)



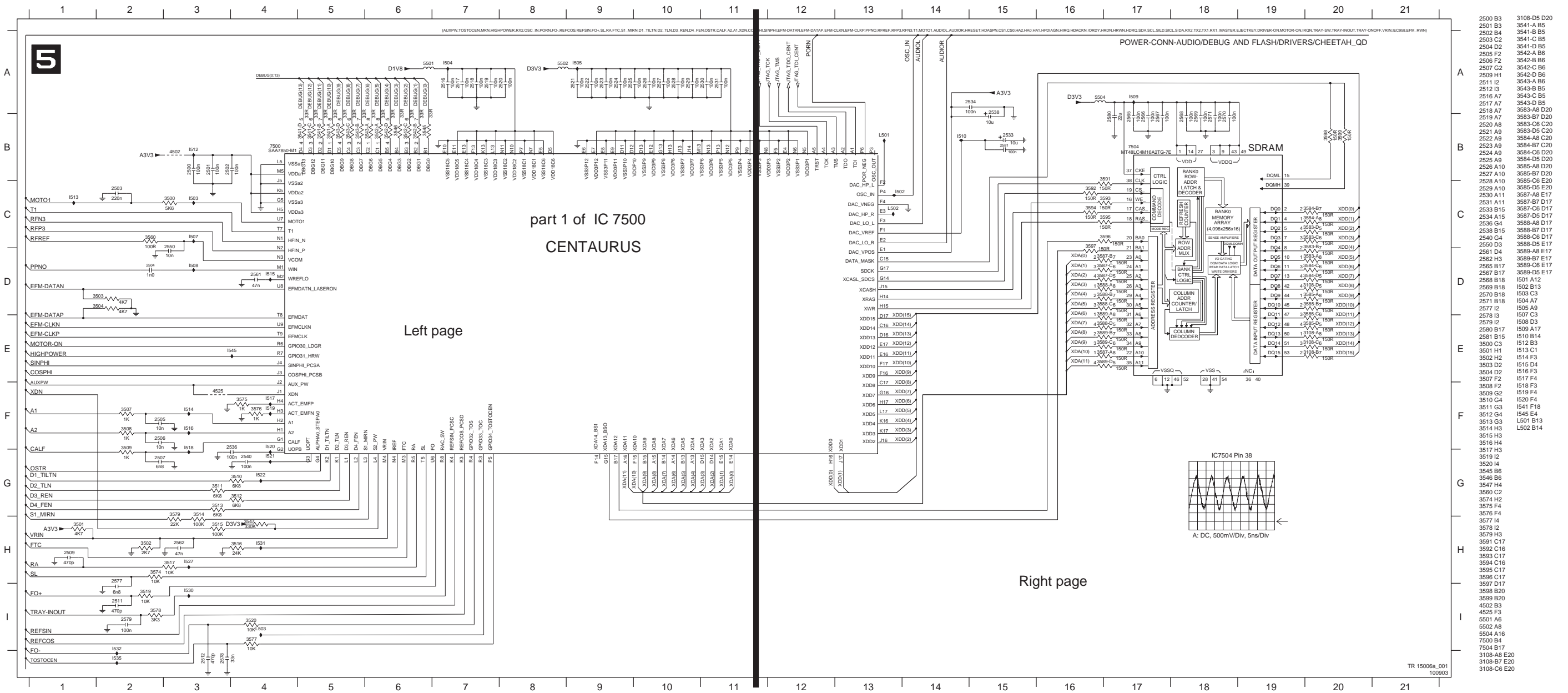
Servo Board: Drivers (Right page)



Right page

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- 2402 B8
- 2403 C5
- 2404 A9
- 2405 B9
- 2406 A7
- 2407 A6
- 2408 C7
- 2409 D6
- 2410 E6
- 2411 J4
- 2412 H3
- 2413 F7
- 2414 G5
- 2415 H4
- 2416 I7
- 2417 I6
- 2418 J4
- 2419 J3
- 2420 J2
- 2421 A9
- 2422 H3
- 2431 E10
- 2432 H2
- 2433 E16
- 2434 G7
- 2435 E16
- 2436 B3
- 2437 H2
- 2438 F18
- 2439 I2
- 2440 J12
- 2441 J14
- 2442 I6
- 2443 H6
- 2444 K7
- 3400 B6
- 3401 B6
- 3402 A6
- 3403 A6
- 3404 B9
- 3405 B8
- 3406 A6
- 3407 D6
- 3408 E6
- 3409 E6
- 3410 F6
- 3411 I7
- 3412 I3
- 3418 H3
- 3420 K5
- 3421 J4
- 3422 K5
- 3423 G7
- 3425 H3
- 3440 C10
- 3441 C11
- 3442 C11
- 3443 C16
- 3444 C11
- 3445 C16
- 3446 C10
- 3447 C11
- 3450 C16
- 3451 C17
- 3452 C11
- 3453 C16
- 3454 D11
- 3455 D11
- 3457 D11
- 3460 D16
- 3461 D10
- 3462 D11
- 3464 D10
- 3471 F19
- 3472 G14
- 3473 G9
- 3474 H9
- 3475 H5
- 3476 H15
- 3477 H9
- 3478 I9
- 3479 I9
- 3480 J13
- 3481 I9
- 3482 H13
- 3483 J13
- 3484 K13
- 3485 J10
- 3486 K14
- 3487 D7
- 3488 F7
- 3489 F19
- 3490 G19
- 3491 F19
- 3492 B10
- 3493 K5
- 3494 K6
- 4400 B12
- 4402 K7
- 4403 C12
- 4404 C15
- 4405 C15
- 4406 D12
- 4407 D13
- 4410 D13
- 4411 D13
- 4413 D16
- 4415 G15
- 4416 G18
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- 5406 E15
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- 7400-B D6
- 7401-A B9
- 7402 H4
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- 7405-B D10
- 7405-C C16
- 7405-D J14
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- 7409 G10
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- I401 B6
- I402 B6
- I403 B8
- I404 B10
- I405 B9
- I406 A7
- I407 A6
- I408 C7
- I409 D6
- I410 E6
- I411 E6
- I413 F7
- I414 F6
- I415 H4
- I416 I7
- I417 I4
- I418 J4
- I419 K5
- I420 H2
- I421 K5
- I422 H3
- I423 H2
- I424 G7
- I425 H2
- I426 B3
- I427 H2
- I428 I2
- I429 I2
- I430 H5
- I431 I2
- I432 G5
- I433 I2
- I434 H4
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- I436 I2
- I437 I2
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- I481 F12
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- I488 K14

Servo Board: Centaurus Part 1 (Overview)



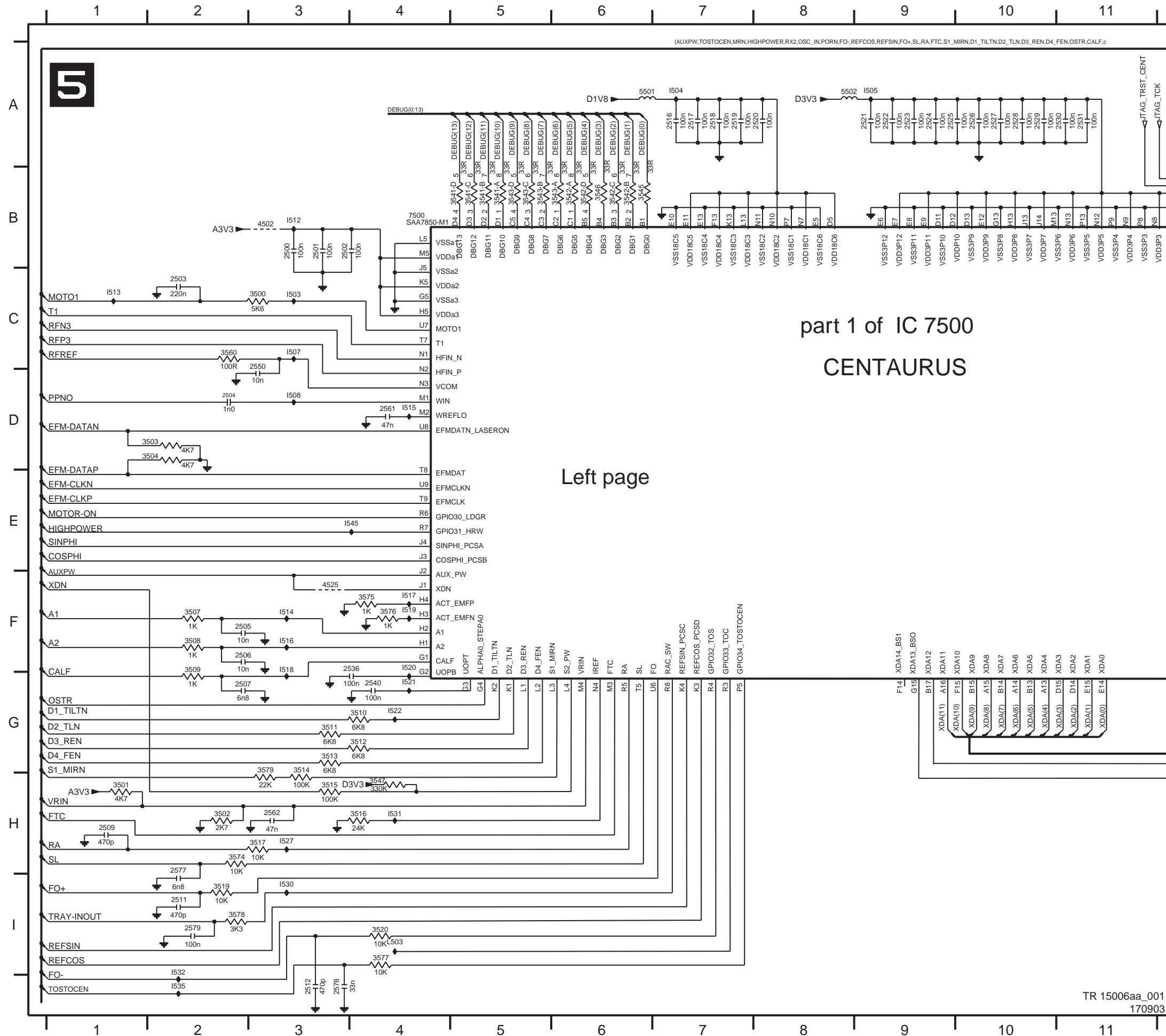
part 1 of IC 7504
CENTAURUS

Left page

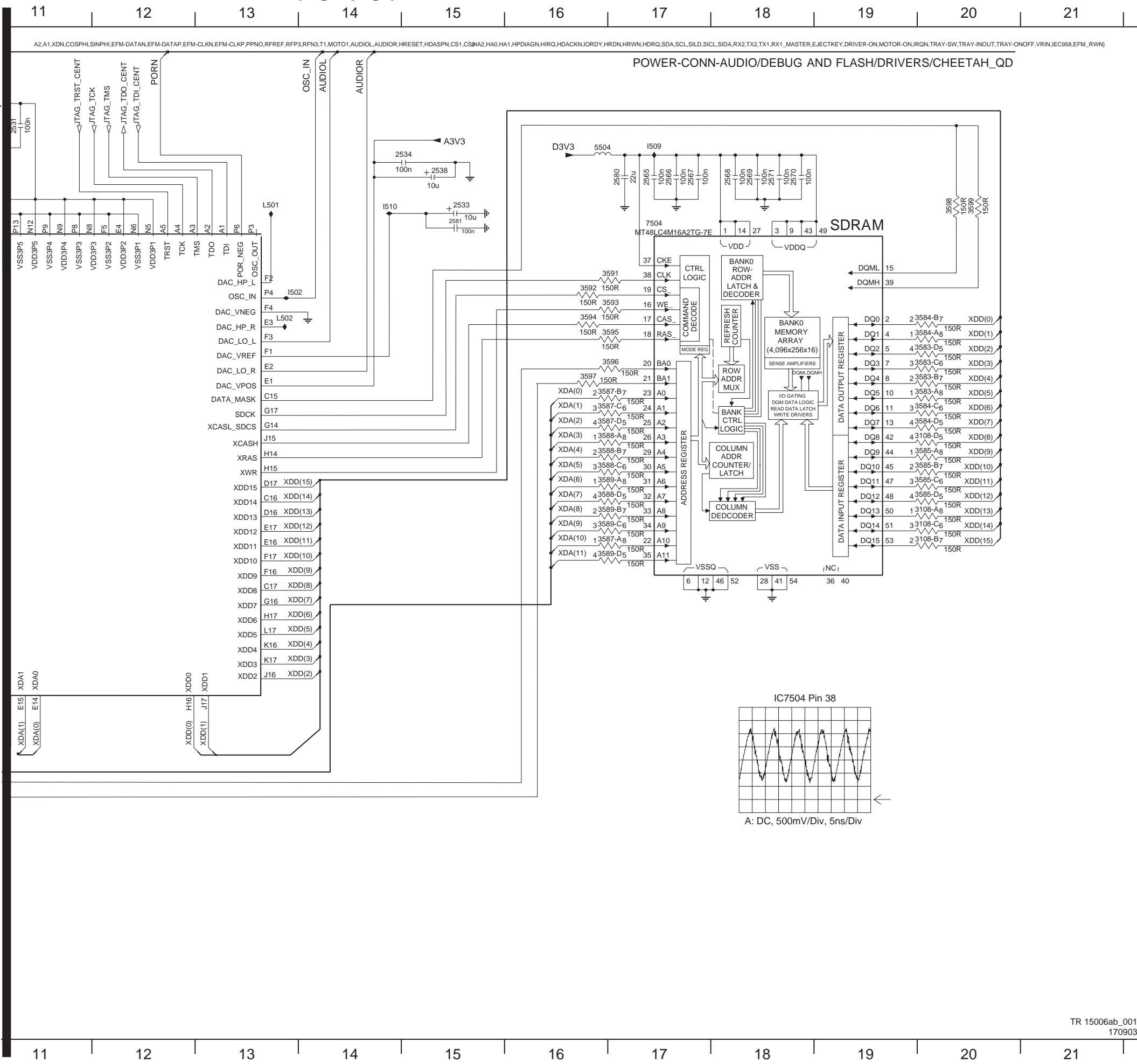
Right page

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- 2503 C2 3541-C B5
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- 2505 F2 3542-A B6
- 2506 F2 3542-B B6
- 2507 G2 3542-C B6
- 2509 H1 3542-D B6
- 2511 I2 3543-A B6
- 2512 I3 3543-B B5
- 2516 A7 3543-C B5
- 2517 A7 3543-D B6
- 2518 A7 3583-A8 D20
- 2519 A7 3583-B7 D20
- 2520 A8 3583-C6 C20
- 2521 A9 3583-D5 C20
- 2522 A9 3584-A8 C20
- 2523 A9 3584-B7 C20
- 2524 A9 3584-C6 D20
- 2525 A9 3584-D5 D20
- 2526 A10 3585-A8 D20
- 2527 A10 3585-B7 D20
- 2528 A10 3585-C6 E20
- 2529 A10 3585-D5 E20
- 2530 A11 3587-A8 E17
- 2531 A11 3587-B7 D17
- 2533 B15 3587-C6 D17
- 2534 A15 3587-D5 D17
- 2535 C4 3588-A8 D17
- 2538 B15 3588-B7 D17
- 2540 G4 3588-C6 D17
- 2541 D4 3588-D5 E17
- 2542 H3 3589-A8 E17
- 2543 H3 3589-B7 E17
- 2545 B17 3589-C6 E17
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- 2548 B18 3589-E17
- 2549 B18 3590-B13
- 2550 B18 3590-C3
- 2551 B18 3590-A7
- 2577 I2 3590-A9
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- 2579 I2 3590-D3
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- 2581 B15 3590-B14
- 3500 C3 3590-B3
- 3501 H1 3590-C1
- 3502 H2 3590-C2
- 3503 D2 3590-D4
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- 3511 G3 3541-F18
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- 3514 H3 3514-H3
- 3515 H3 3515-H3
- 3516 H4 3516-H4
- 3517 H3 3517-H3
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- 3545 B6 3545-B6
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- 3560 C2 3560-C2
- 3574 H2 3574-H2
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- 3592 C16 3592-C16
- 3593 C17 3593-C17
- 3594 C16 3594-C16
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- 3596 C17 3596-C17
- 3597 D17 3597-D17
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- 5502 A8 5502-A8
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- 7504 B17 7504-B17
- 3108-A8 E20 3108-A8 E20
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- 3108-C6 E20 3108-C6 E20

Servo Board: Centaurus Part 1 (Left page)

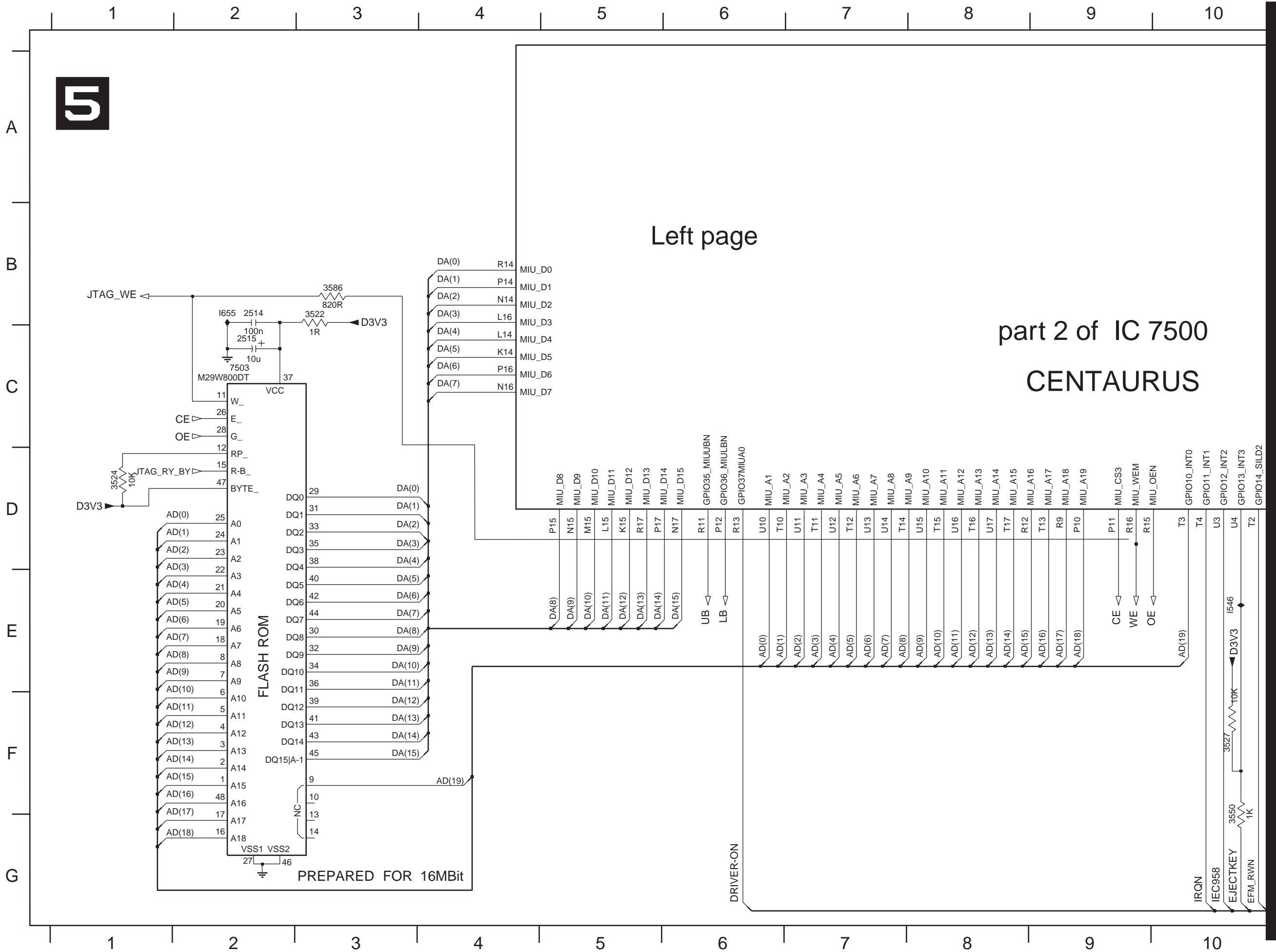


Servo Board: Centaurus Part 1 (Right page)

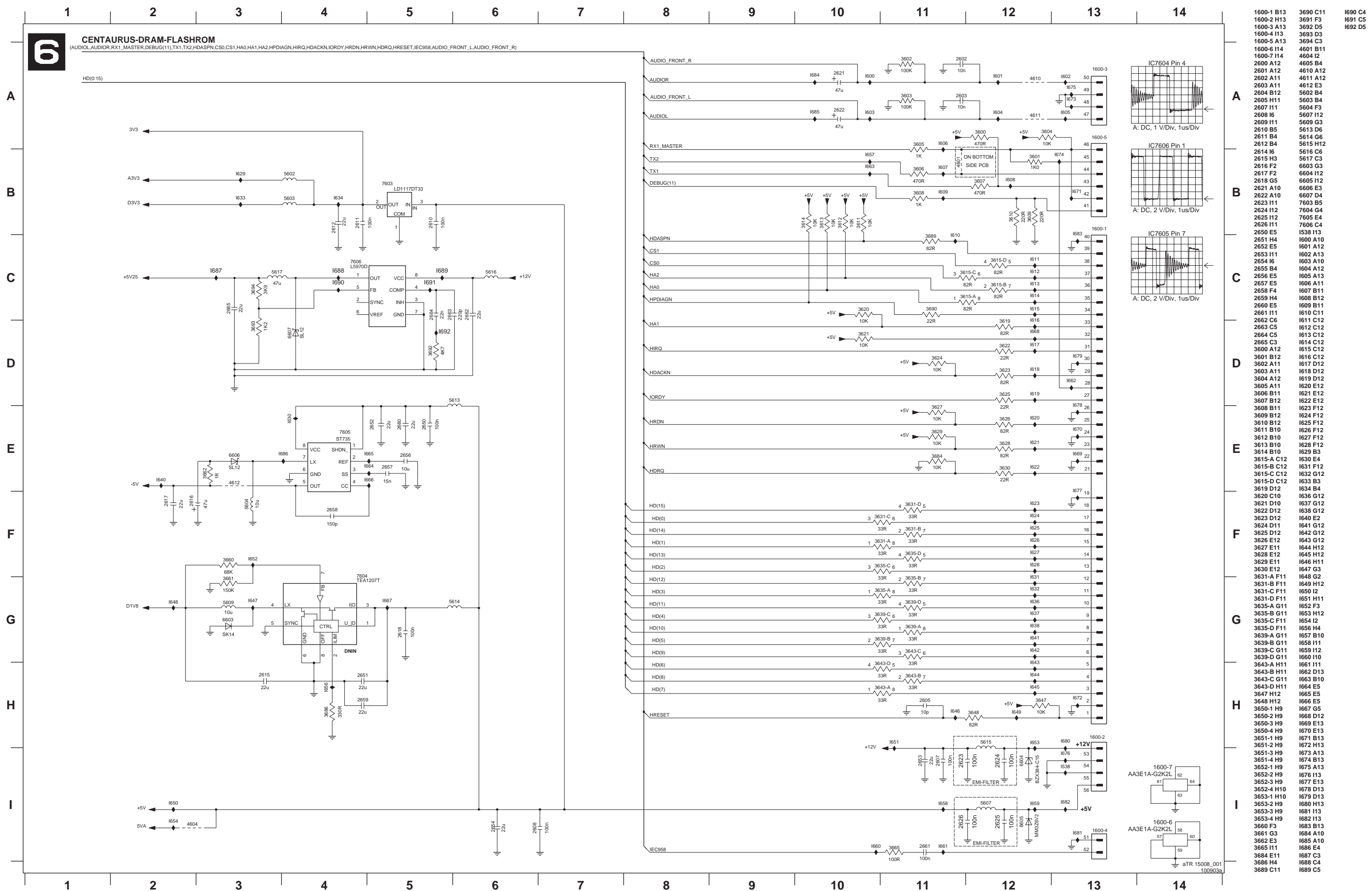


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- 2505 F2 3542-A B6
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- 2507 G2 3542-C B6
- 2509 H1 3542-D B6
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- 2512 I3 3543-B B5
- 2516 A7 3543-C B5
- 2517 A7 3543-D B5
- 2518 A7 3583-A8 D20
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- 2520 A8 3583-C6 C20
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- 2522 A9 3584-A8 C20
- 2523 A9 3584-B7 C20
- 2524 A9 3584-C6 D20
- 2525 A9 3584-D5 D20
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- 2527 A10 3585-B7 D20
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- 2531 A11 3587-B7 D17
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- 2534 A15 3587-D5 D17
- 2536 G4 3588-A8 D17
- 2538 B15 3588-B7 D17
- 2540 G4 3588-C6 D17
- 2550 D3 3588-D5 E17
- 2561 D4 3589-A8 E17
- 2562 H3 3589-B7 E17
- 2565 B17 3589-C6 E17
- 2567 B17 3589-D5 E17
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- 2569 B18 502 B13
- 2570 B18 503 C3
- 2571 B18 504 A7
- 2577 I2 505 A9
- 2578 I3 507 C3
- 2579 I2 508 D3
- 2580 B17 509 A17
- 2581 B15 510 B14
- 3500 C3 512 B3
- 3501 H1 513 C1
- 3502 H2 514 F3
- 3503 D2 515 D4
- 3504 D2 516 F3
- 3507 F2 517 F4
- 3508 F2 518 F3
- 3509 G2 519 F4
- 3510 G4 520 F4
- 3511 G3 541 F18
- 3512 G4 545 E4
- 3513 G3 501 B13
- 3514 H3 502 B14
- 3515 H3
- 3516 H4
- 3517 H3
- 3519 I2
- 3520 I4
- 3545 B6
- 3546 B6
- 3547 H4
- 3560 C2
- 3574 H2
- 3575 F4
- 3576 F4
- 3577 I4
- 3578 I2
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- 3592 C16
- 3593 C17
- 3594 C16
- 3595 C17
- 3596 C17
- 3597 D17
- 3598 B20
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- 4502 B3
- 4525 F3
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- 5502 A8
- 5504 A16
- 7500 B4
- 7504 B17
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- 3108-B7 E20
- 3108-C6 E20

Servo Board: Centaurus Part 2 (Left page)



Servo Board: Power, Connectors



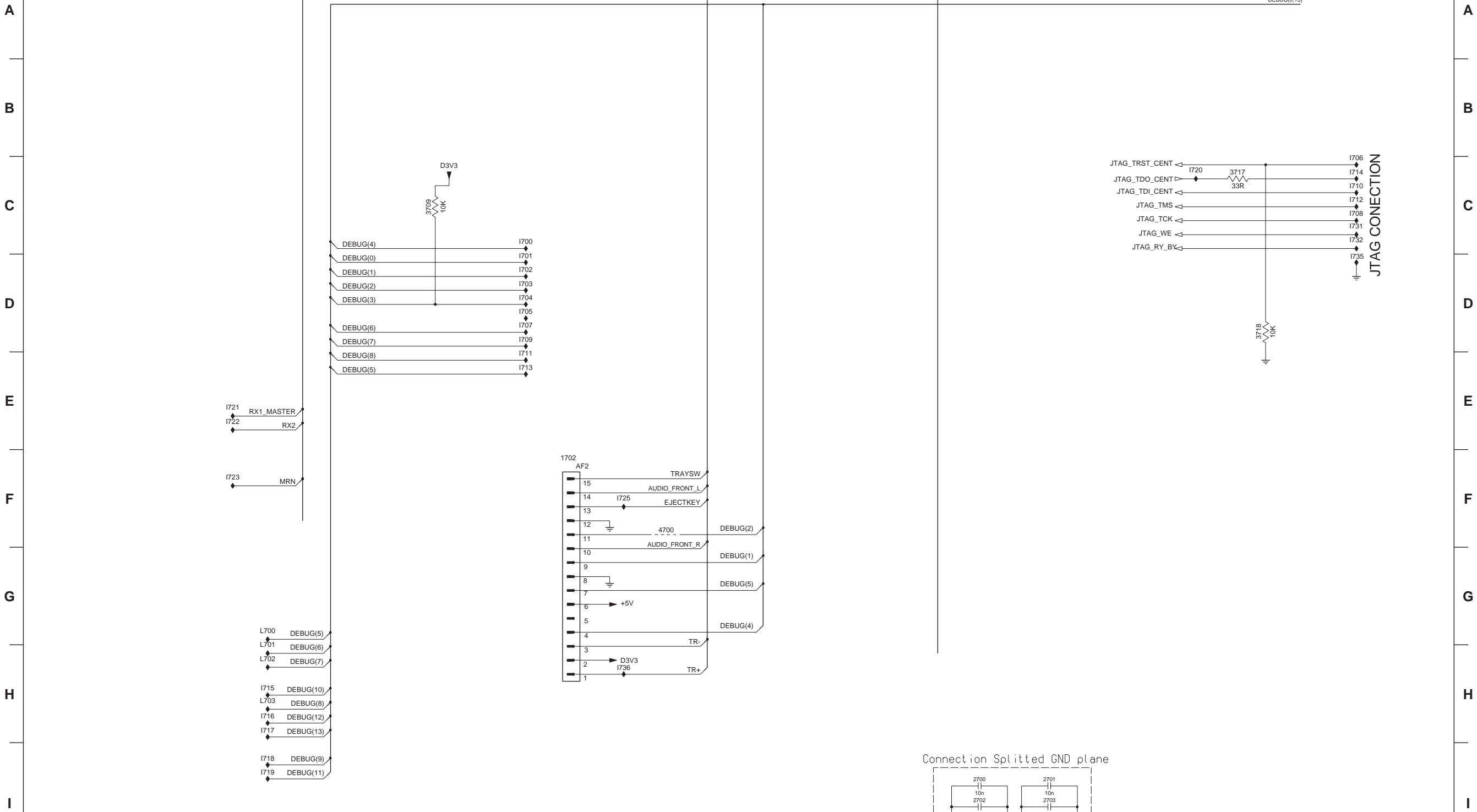
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| 1600-1 B13 | 3690 C11 | 1690 C4 |
| 1600-2 H13 | 3691 F3 | 1691 C5 |
| 1600-3 A13 | 3692 D5 | 1692 D5 |
| 1600-4 I13 | 3693 D3 | |
| 1600-5 A13 | 3694 C3 | |
| 1600-6 I14 | 4601 B11 | |
| 1600-7 I14 | 4604 I2 | |
| 2600 A12 | 4605 B4 | |
| 2601 A12 | 4610 A12 | |
| 2602 A11 | 4611 A12 | |
| 2603 A11 | 4612 E3 | |
| 2604 B12 | 5602 B4 | |
| 2605 H11 | 5603 B4 | |
| 2607 I11 | 5604 F3 | |
| 2608 I6 | 5607 I2 | |
| 2609 H11 | 5609 G3 | |
| 2610 B5 | 5613 D6 | |
| 2611 B4 | 5614 G6 | |
| 2612 B4 | 5615 H12 | |
| 2614 I6 | 5616 C6 | |
| 2615 H3 | 5617 C3 | |
| 2616 F2 | 6603 G3 | |
| 2617 F2 | 6604 I2 | |
| 2618 G5 | 6605 I2 | |
| 2621 A10 | 6606 E3 | |
| 2622 A10 | 6607 D4 | |
| 2623 I11 | 7603 B5 | |
| 2624 I12 | 7604 G4 | |
| 2625 I12 | 7605 E4 | |
| 2626 I11 | 7606 C4 | |
| 2650 E5 | 1538 I13 | |
| 2651 H4 | 1600 A10 | |
| 2652 E5 | 1601 A12 | |
| 2653 H11 | 1602 A13 | |
| 2654 I6 | 1603 A16 | |
| 2655 B4 | 1604 A12 | |
| 2656 E5 | 1605 A13 | |
| 2657 E5 | 1606 A11 | |
| 2658 F4 | 1607 B11 | |
| 2659 H4 | 1608 B12 | |
| 2660 E5 | 1609 B11 | |
| 2661 H11 | 1610 C11 | |
| 2662 C6 | 1611 C12 | |
| 2663 C5 | 1612 C12 | |
| 2664 C5 | 1613 C12 | |
| 2665 C3 | 1614 C12 | |
| 3600 A12 | 1615 C12 | |
| 3601 B12 | 1616 C12 | |
| 3602 A11 | 1617 D12 | |
| 3603 A11 | 1618 D12 | |
| 3604 A12 | 1619 D12 | |
| 3605 A11 | 1620 E12 | |
| 3606 B11 | 1621 E12 | |
| 3607 B12 | 1622 E12 | |
| 3608 B11 | 1623 F12 | |
| 3609 B12 | 1624 F12 | |
| 3610 B12 | 1625 F12 | |
| 3611 B10 | 1626 F12 | |
| 3612 B10 | 1627 F12 | |
| 3613 B10 | 1628 F12 | |
| 3614 B10 | 1629 B3 | |
| 3615-A C12 | 1630 E4 | |
| 3615-B C12 | 1631 F12 | |
| 3615-C C12 | 1632 G12 | |
| 3615-D C12 | 1633 B3 | |
| 3619 D12 | 1634 B4 | |
| 3620 C10 | 1635 G12 | |
| 3621 D10 | 1637 G12 | |
| 3622 D12 | 1638 G12 | |
| 3623 D12 | 1640 E2 | |
| 3624 D11 | 1641 G12 | |
| 3625 D12 | 1642 G12 | |
| 3626 E12 | 1643 G12 | |
| 3627 E11 | 1644 H12 | |
| 3628 E12 | 1645 H12 | |
| 3629 E11 | 1646 H11 | |
| 3630 E12 | 1647 G3 | |
| 3631-A F11 | 1648 G2 | |
| 3631-B F11 | 1649 H12 | |
| 3631-C F11 | 1650 I2 | |
| 3631-D F11 | 1651 H11 | |
| 3635-A G11 | 1652 F3 | |
| 3635-B G11 | 1653 H12 | |
| 3635-C F11 | 1654 I2 | |
| 3635-D F11 | 1656 H4 | |
| 3639-A G11 | 1657 B10 | |
| 3639-B G11 | 1658 H11 | |
| 3639-C G11 | 1659 I12 | |
| 3639-D G11 | 1660 I10 | |
| 3643-A H11 | 1661 H11 | |
| 3643-B H11 | 1662 D13 | |
| 3643-C G11 | 1663 B10 | |
| 3643-D H11 | 1664 E5 | |
| 3647 H12 | 1665 E5 | |
| 3648 H12 | 1666 E5 | |
| 3650-1 H9 | 1667 G5 | |
| 3650-2 H9 | 1668 D12 | |
| 3650-3 H9 | 1669 E13 | |
| 3650-4 H9 | 1670 E13 | |
| 3651-1 H9 | 1671 B13 | |
| 3651-2 H9 | 1672 H13 | |
| 3651-3 H9 | 1673 A13 | |
| 3651-4 H9 | 1674 B13 | |
| 3652-1 H9 | 1675 A13 | |
| 3652-2 H9 | 1676 H13 | |
| 3652-3 H9 | 1677 E13 | |
| 3652-4 H10 | 1678 D13 | |
| 3653-1 H10 | 1679 D13 | |
| 3653-2 H9 | 1680 H13 | |
| 3653-3 H9 | 1681 H13 | |
| 3653-4 H9 | 1682 I13 | |
| 3660 F3 | 1683 B13 | |
| 3661 G3 | 1684 A10 | |
| 3662 E3 | 1685 A10 | |
| 3665 H11 | 1686 E4 | |
| 3684 E11 | 1687 C3 | |
| 3686 H4 | 1688 C4 | |
| 3689 C11 | 1689 C5 | |

Servo Board: Tray Motor Connections

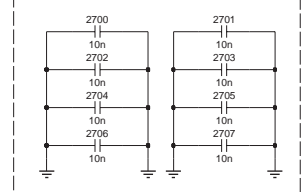
OPU/CHEETAH_QD/DRIVERS/CENTAURUS/POWER-CONN

(RAD,SERVO-COMM,MOTO1,MRN,RX1_MASTER,TX1,A1,A2,CALF,VRIN,D1,TILT,D2,TUN,D3_REN,D4_FEN,S1_MIRN,S2_FTC,MON1,MON2,RX2,TX2,PPNO,IRGN,PORN,T1,SCL,SDA,XDN,DRIVER-ON,FO-,FO+,VFOO-,VFOO+,RA,VRAGO,SL+,SL-,FOC+,FOC-AUDIO_FRONT_L,AUDIO_FRONT_R,TR+,TR-,TRAYSW,EJECTKEY,SLVSLOO,V,MOTO10)

7



Connection Splitted GND plane



- 0001 I7
- 0002 I8
- 1700 B1
- 1702 F6
- 1703 C6
- 1705 E9
- 2700 I10
- 2701 I11
- 2702 I10
- 2703 I11
- 2704 I10
- 2705 I11
- 2706 I10
- 2707 I11
- 3702 H5
- 3703 H5
- 3704 H5
- 3705 H5
- 3706 I5
- 3707 I5
- 3708 C5
- 3709 C4
- 3710 C4
- 3711 C4
- 3712 C5
- 3713 B13
- 3714 B13
- 3715 B13
- 3716 B13
- 3717 C13
- 3718 D13
- 3719 D13
- 4700 F7
- 4701-A B2
- 4701-B B2
- 4701-C B2
- 4701-D C2
- 4702-A C2
- 4702-B C2
- 4702-C C2
- 4702-D D2
- 4703-A D2
- 4703-B D2
- 4703-C C2
- 4703-D C2
- 4704-A E2
- 4704-B E2
- 4704-C D2
- 4704-D E2
- 4705-A D2
- 4705-B F2
- 4705-C F2
- 4705-D E2
- 4706-A F2
- 4706-B F2
- 4706-C F2
- 4706-D D2
- 4707 F2
- I700 C5
- I701 D5
- I702 D5
- I703 D5
- I704 D5
- I705 D5
- I706 C14
- I707 D5
- I708 C14
- I709 D5
- I710 C14
- I711 E5
- I712 C14
- I713 E5
- I714 C14
- I715 H3
- I716 H3
- I717 H3
- I718 I3
- I719 I3
- I720 C12
- I721 E2
- I722 E2
- I723 F2
- I725 F6
- I731 C14
- I732 C14
- I733 D14
- I736 H6
- L700 G3
- L701 G3
- L702 H3
- L703 H3

8. Alignments

In case of a change of DVD-M or PWB a readjustment is necessary to align the OPU and PWB to each other.

8.1 Necessary Tools

- Personal computer with Windows 2000™ or Windows XP™
- USB to ATAPI adapter, (standard computer equipment) see figure 8-1.
- "Applicator software" (v2.85.00).

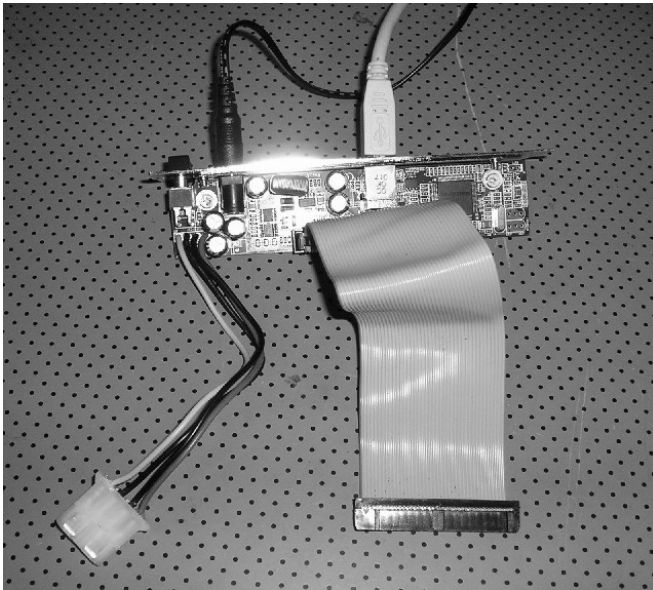


Figure 8-1 , USB to ATAPI adapter

8.2 Adjustment Procedure

- Connect the basic engine to the USB to ATAPI adapter
- Power on the adapter
- Connect the USB connector of the adapter to the PC.

Note that the USB bus supports "Hot Plugging". That means the computer can already be switched on.

Alternatively you can connect the basic engine directly to the IDE bus of a computer. In this case the adapter is not necessary but the PC has to be switched off and must be started up in order to detect the new drive on the IDE bus.

- Call up the applicator software, see figure 8-2
- Set the timeout to 50 seconds, see figure 8-3
- Run the "Adjust Laser Control" command, see figure 8-4.
- The "Status" indicator in the left section of the window has to become green after successful adjustment.

After repairing the drive it should be tested at least with the following discs:

1. LVP 12.01 (710409991731) test layer change on track 28 ->31
2. DVD+R disc. Use Disc type Ricoh 4X DVD+R
 - Record 1 minute
 - press stop
 - Open / close
 - Play back recorded track
3. CD-RW low reflection audio disc. (7104 099 96581)



Figure 8-2 , Applicator Software

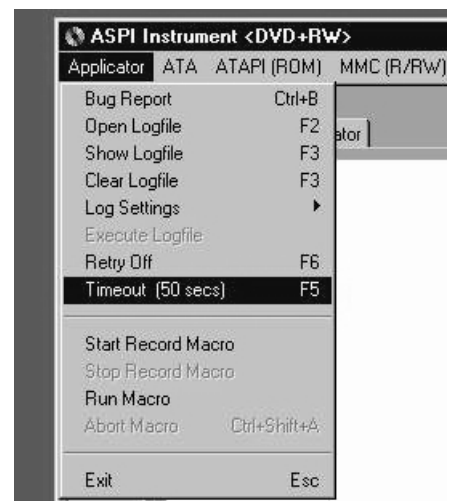


Figure 8-3 , Set Timeout

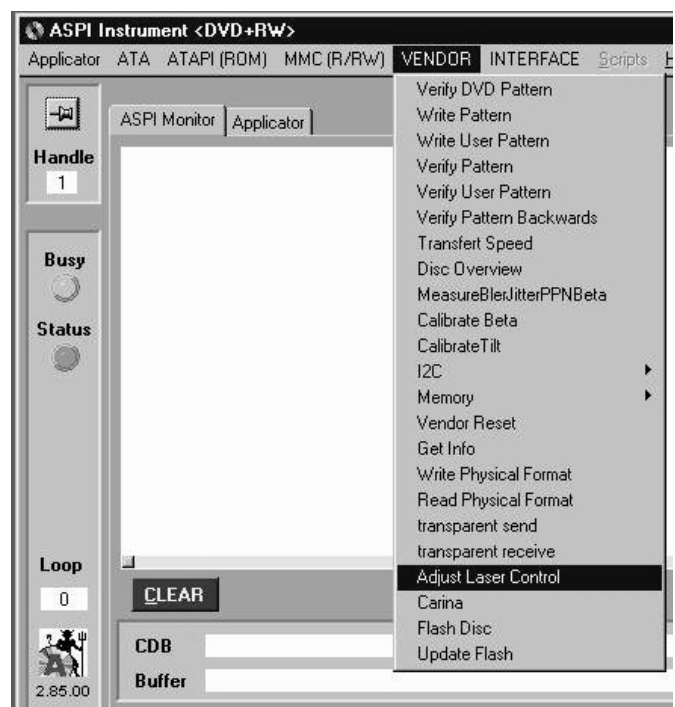


Figure 8-4 , Run Adjust Laser Control

9.5 Laconic

The main function of the LACONIC, IC7300 is to control the laser power. The IC forms a closed control loop in combination with the Elantec located on the OPU. It compensates aging and temperature of the laser. Furthermore it forms a fingerprint correction loop. It also acts as bridge between IIC and serial bus of the Elantec laser driver on the OPU.

9.6 Optical Pick-up Unit

The OPU66 is a dual laser Optical Pick-up Unit for DVD+RW/+R. It consists of a 3-D actuator for focusing, radial tracking and tilt correction.

- 650nm laser for DVD
- 780nm laser for CD

On the interconnecting flex several electrical components are mounted.

- Elantec programmable laser diode power driver
- Paedic integrated photo detector with programmable gain pre-amplifier
- Eeprom containing a number of values representing adjustments belonging to the OPU.

The laser control and diode signal processor ICs together with an EEPROM are mounted on the OPU flex.

The laser control IC generates the DVD laser read and writing signals needed for reading DVD discs and writing DVD+RW / +R discs (write strategies of DVD+RW / +R discs).

The diode signal processor is an analogue pre-processor adapted for the CD and CD-R / RW read function.

The EEPROM contains information about writing current, writing strategies and other parameters belonging to the OPU.

9.7 Motor and Servo drivers

A Servo Driver is implemented to control the sledge. Several motor driver ICs are incorporated to control the Tray, Disc and Turntable motors,

Driver ICs are incorporated for control of the:

- Actuator
- Disc Motor
- Sledge Motor
- Tray Motor

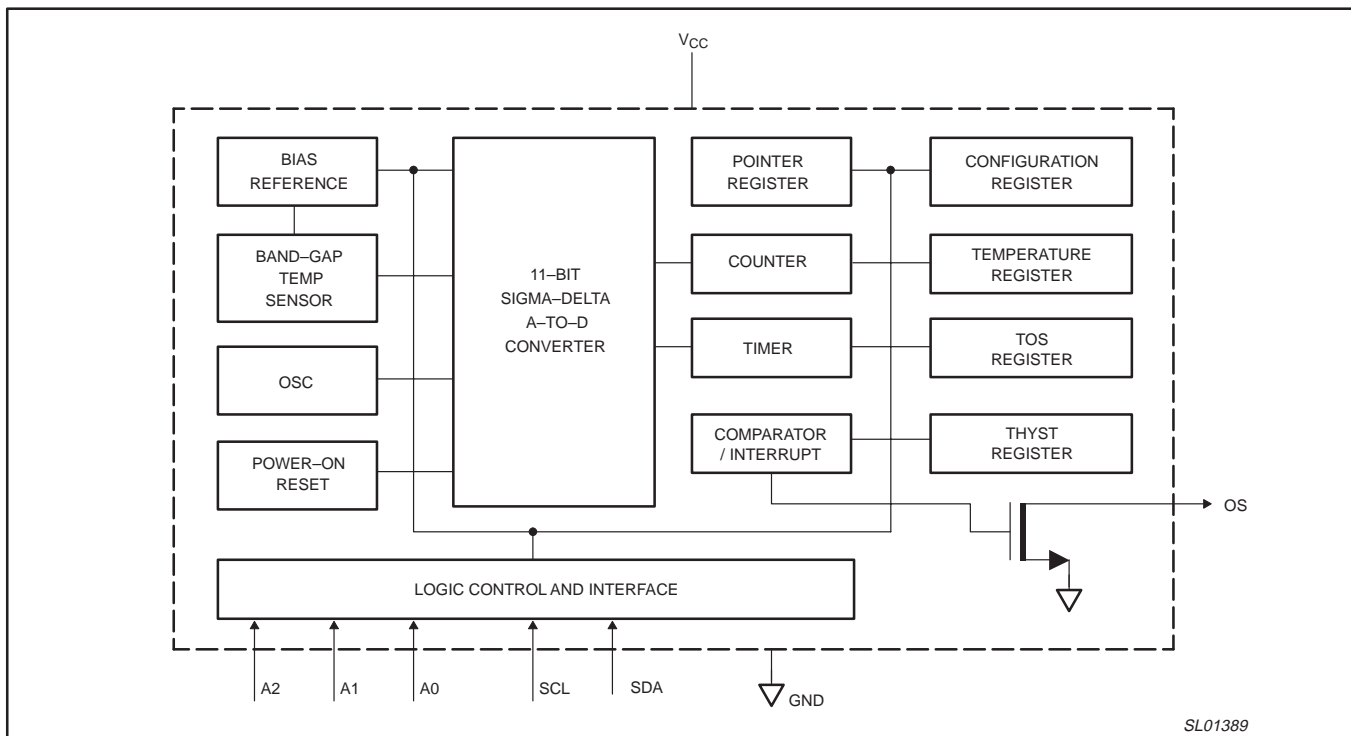
9.8 ICs Servo Board

IC7105, LM75A: Servo Board, Temperature Sensor

Pin description

| PIN | SYMBOL | DESCRIPTION |
|-----|-----------------|--|
| 1 | SDA | Digital I/O. I ² C serial bi-directional data line. Open Drain. |
| 2 | SCL | Digital input. I ² C serial clock input. |
| 3 | OS | Overtemp Shutdown output. Open Drain. |
| 4 | GND | Ground. To be connected to the system ground. |
| 5 | A2 | Digital input. User-defined address bit2. |
| 6 | A1 | Digital input. User-defined address bit1. |
| 7 | A0 | Digital input. User-defined address bit0. |
| 8 | V _{CC} | Power supply. |

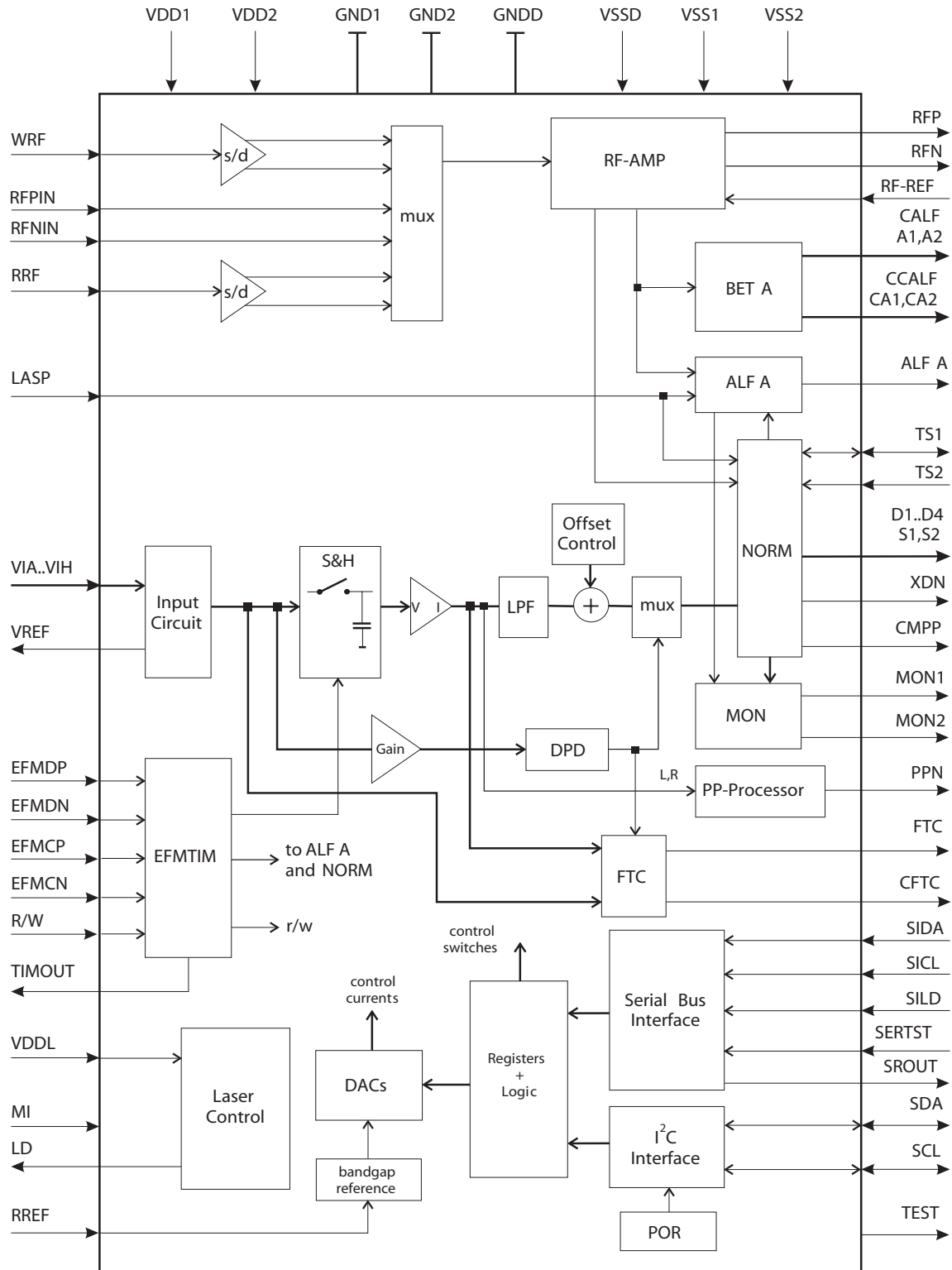
SIMPLIFIED BLOCK DIAGRAM



SL01389

IC7201, TZA1039HL: Servo Board, Analogue Preprocessor

BLOCK DIAGRAM



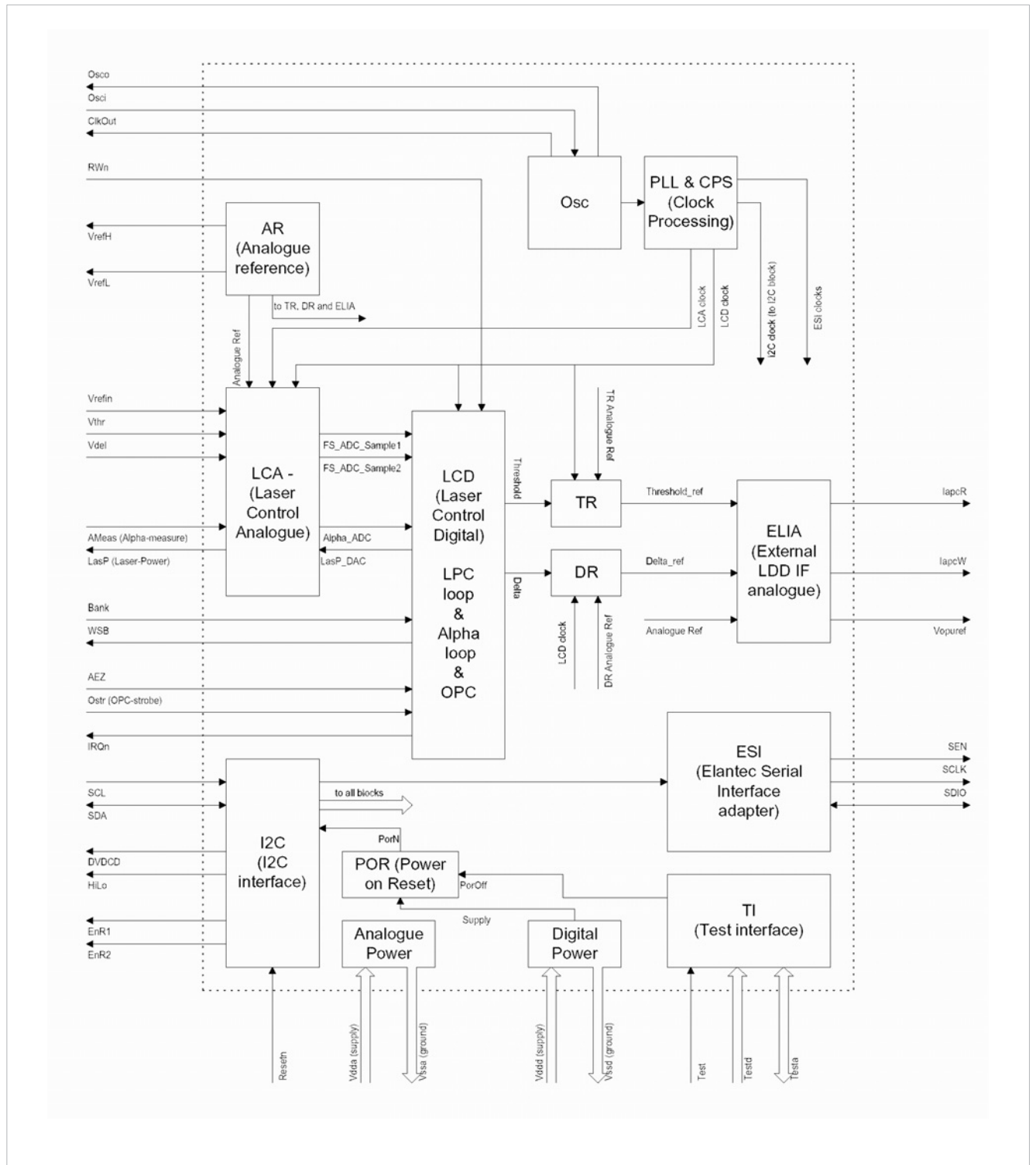
PINNING

| SYMBOL | PIN | DESCRIPTION |
|--------|-----|--|
| VIH | 1 | Satelite segment H input |
| GND1 | 2 | Ground |
| VIC | 3 | Central segment C input |
| VIB | 4 | Central segment B input |
| GND1 | 5 | Ground |
| RFNIN | 6 | Inverse differential RF input |
| RFPIN | 7 | Differential RF input |
| VDD1 | 8 | Positive supply |
| VID | 9 | Central segment D input |
| VIA | 10 | Central segment A input |
| VDD1 | 11 | Positive supply |
| VIE | 12 | Satelite segment E input |
| VIG | 13 | Satelite segment G input |
| R/W | 14 | External Read/Write signal input |
| N.C. | 15 | Not connected |
| N.C. | 16 | Not connected |
| N.C. | 17 | Not connected |
| TIMOUT | 18 | EFMTIM test output |
| VSSD | 19 | Negative supply |
| EFMCN | 20 | Inverse EFM clock input |
| EFMCP | 21 | EFM clock input |
| EFMDN | 22 | Inverse EFM data input |
| EFMDP | 23 | EFM data input |
| GNDD | 24 | Ground |
| SDA | 25 | Data input/output I2C |
| SCL | 26 | Clock input I2C |
| N.C. | 27 | Not connected |
| FTC | 28 | FTC output |
| CFTC | 29 | FTC high pass lter capacitor |
| TS2 | 30 | Tilt sensor input current |
| TS1 | 31 | Tilt sensor input current |
| SILD | 32 | Strobe line of serial bus interface |
| N.C. | 33 | Not connected |
| SIDA | 34 | Data line of serial bus interface |
| SICL | 35 | Clock line of serial bus interface |
| VDD2 | 36 | Positive supply voltage |
| GND2 | 37 | Supply ground |
| RFP | 38 | RF output voltage, positive |
| RFN | 39 | RF output voltage, negative |
| VSS2 | 40 | Negative supply voltage |
| RFREF | 41 | Reference voltage for differential RF output common mode level |
| PPNO | 42 | Output PP voltage |

| SYMBOL | PIN | DESCRIPTION |
|--------|-----|--|
| N.C. | 43 | Not connected |
| N.C. | 44 | Not connected |
| SERTST | 45 | Enable test mode (Tie to GND for normal operation) |
| VSSD | 46 | Negative supply voltage |
| GNDD | 47 | Supply ground |
| CA1 | 48 | Beta circuit external capacitor |
| CA2 | 49 | Beta circuit external capacitor |
| CCALF | 50 | Beta circuit external capacitor |
| VSS1 | 51 | Negative supply voltage |
| RREF | 52 | Reference resistor to VSS |
| GND1 | 53 | Supply ground |
| CMPP | 54 | MPP external capacitor |
| VDD1 | 55 | Positive supply |
| MON1 | 56 | Monitor output voltage |
| MON2 | 57 | Monitor output voltage |
| S2 | 58 | Servo output current |
| S1 | 59 | Servo output current |
| D4 | 60 | Servo output current |
| D3 | 61 | Servo output current |
| D2 | 62 | Servo output current |
| D1 | 63 | Servo output current |
| XDN | 64 | X-position output voltage |
| CALF | 65 | RF average level signal |
| A2 | 66 | RF bottom level signal |
| A1 | 67 | RF top level signal |
| SROUT | 68 | shift register output for register test mode |
| ALFA | 69 | alfa output current |
| LASP | 70 | laser power setpoint signal |
| TEST | 71 | Test output |
| N.C. | 72 | Not connected |
| MI | 73 | Monitor input for laser |
| LD | 74 | Drive current for laser |
| VDDL | 75 | Laser supply voltage |
| RRF | 76 | Single-ended RF read input |
| WRF | 77 | Single-ended RF writeinput |
| VSS1 | 78 | Negative supply |
| VREF | 79 | PDIC reference voltage output |
| VIF | 80 | Satelite segment F input |

IC7300, TZA1042: Servo Board, Laser Power Controller

Block diagram



Pin description

| Symbol | Pin | Type | Drive /Thr. | Description |
|-------------------|-----|---------|-------------|---|
| AEZ | 1 | I hy pd | T | Alpha Error Zero/Alpha Set Zero |
| V _{DDD3} | 2 | P | - | Digital Pad Supply |
| V _{SSD3} | 3 | P | - | Digital Pad Supply |
| CLOCKOUT | 4 | T | M | Buffered Oscillator Output |
| OSCO | 5 | AO | A | Output of inverting Amplifier that forms oscillator |
| OSCI | 6 | AI | A | Input of inverting Amplifier that forms oscillator |
| TEST1D | 7 | I pd | T | Test pin |
| AMEAS | 8 | AI | A | Alpha Measure – value of measured disk writing quality |
| V _{DDA1} | 9 | P | - | Analogue Supply |
| V _{SSA1} | 10 | P | - | Analogue Supply |
| LASP | 11 | AO | A | Laser Power – indicates power level |
| VREFL | 12 | AO | A | Bandgap Voltage Reference ground connection |
| VREFH | 13 | AO | A | Bandgap Voltage Reference output |
| VDEL | 14 | AI | A | Voltage input for Delta “laser power” |
| VTHR | 15 | AI | A | Voltage input for Threshold “laser power” |
| VOPUREF | 16 | AO | A | Reference Voltage for OPU |
| VREFIN | 17 | AI | A | Input Reference Voltage for Vthr and Vdel |
| V _{DDA2} | 18 | P | - | Analogue Supply |
| V _{SSA2} | 19 | P | - | Analogue Supply |
| TEST1A | 20 | AB | A | Test pin |
| IAPCW | 21 | AO | A | Current Output of Delta Reference |
| IAPCR | 22 | AO | A | Current Output of Threshold Reference |
| TEST2A | 23 | AB | A | Test pin |
| ENR2 | 24 | T | M | Programmable Output Flag |
| ENR1 | 25 | B pd | M/T | Device Initialisation/Programmable Output Flag (must be driven to VDD during reset) |
| DVDCD | 26 | T | M | Programmable Output Flag for indicating DVD/CD mode |
| HILO | 27 | T | M | Programmable Output Flag for indicating High/Low reflectivity |
| V _{SSD1} | 28 | P | - | Digital Pad Supply |
| V _{DDD1} | 29 | P | - | Digital Pad Supply |
| BUSY | 30 | B | M/T | Busy Enable input from Elantec / Board test IO |
| SEN | 31 | B | M/T | Serial Enable output to Elantec / Board test IO |
| SDIO | 32 | B | M/T | Serial data input output from/to Elantec / Board test IO |
| SCLK | 33 | B | M/T | Busy Enable input from Elantec / Board test IO |
| WSB | 34 | B | M/T | Write Strategy Bank – output controls OPU write switching / Board test IO |

Pin description...continued

| Symbol | Pin | Type | Drive /Thr. | Description |
|-------------------|-----|------------|-------------|--|
| IRQN | 35 | OD | M | Interrupt Request Not – active low interrupt request |
| OSTR | 36 | I hy pd | T | OPC Strobe – request step in alpha setpoint / Board test input |
| RESETN | 37 | I hy pd | T | Reset Not – active low reset input |
| RWN | 38 | B | M/T | Read/Write not – indicates power setpoints/Board test IO |
| V _{SSD2} | 39 | P | - | Digital Core Supply |
| V _{DDD2} | 40 | P | - | Digital Core Supply |
| BANK | 41 | I hy pd | T | CAV setpoint switching input signal / Board test IO |
| TEST2D | 42 | I pd | T | Test pin |
| SDA | 43 | BOD | M/T | I ² C Serial Data |
| SCL | 44 | I | T | I ² C Serial Clock |

[1] All supply pins must be connected to the same external power supply voltage

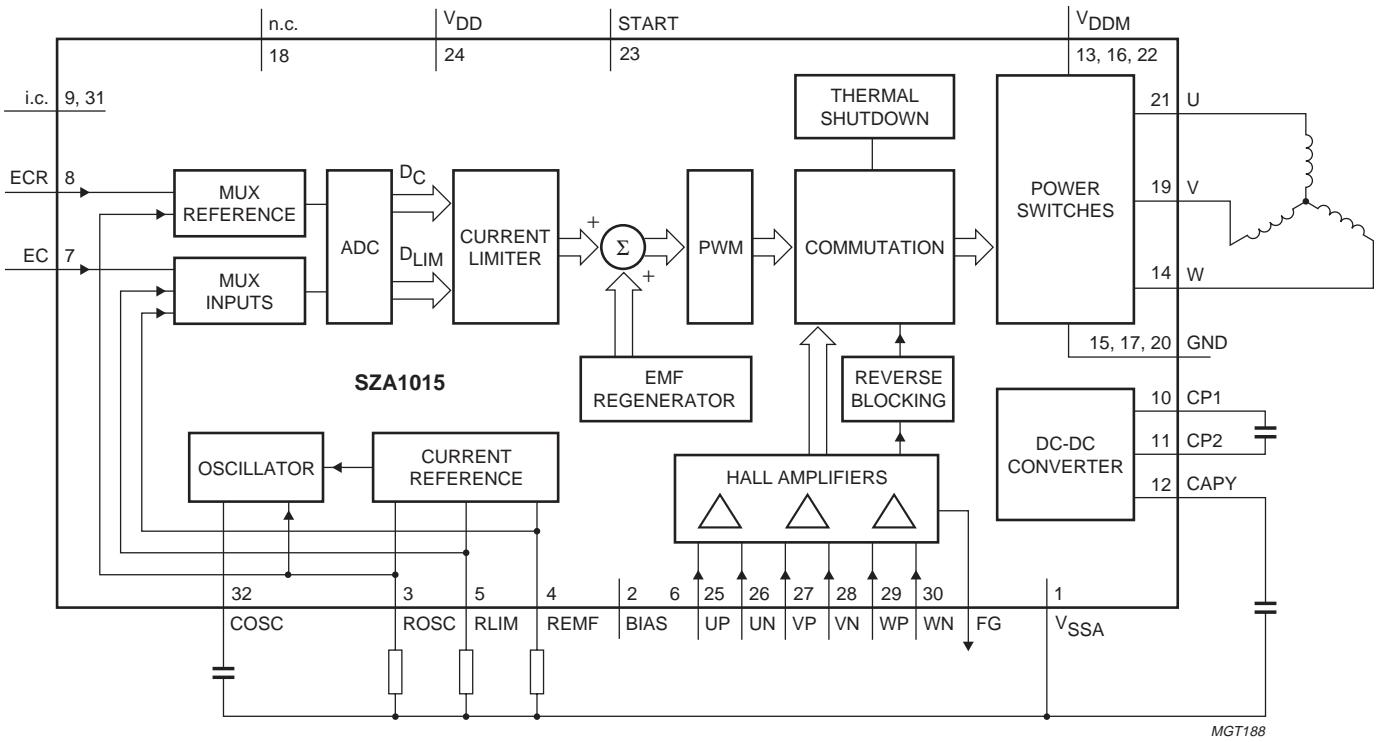
[2] All inputs are 5V tolerant – i.e. they will drive the supply voltage (3.0-3.6V), but will work correctly when interface to a 5V drive device

[3] The pin type definition is given below:

PinType Definition Table

| Type | Definition |
|------|------------------------------|
| I | input |
| O | output |
| OD | open drain |
| B | bi-directional |
| BOD | bi-directional open drain |
| T | tri-state output |
| AI | analog input |
| AO | analog output |
| AB | analog bi-directional |
| P | power connection |
| hy | hysteresis on input |
| pd | hysteresis on output |

IC7402, SZA1015: Servo Board, Brushless Motor Controller

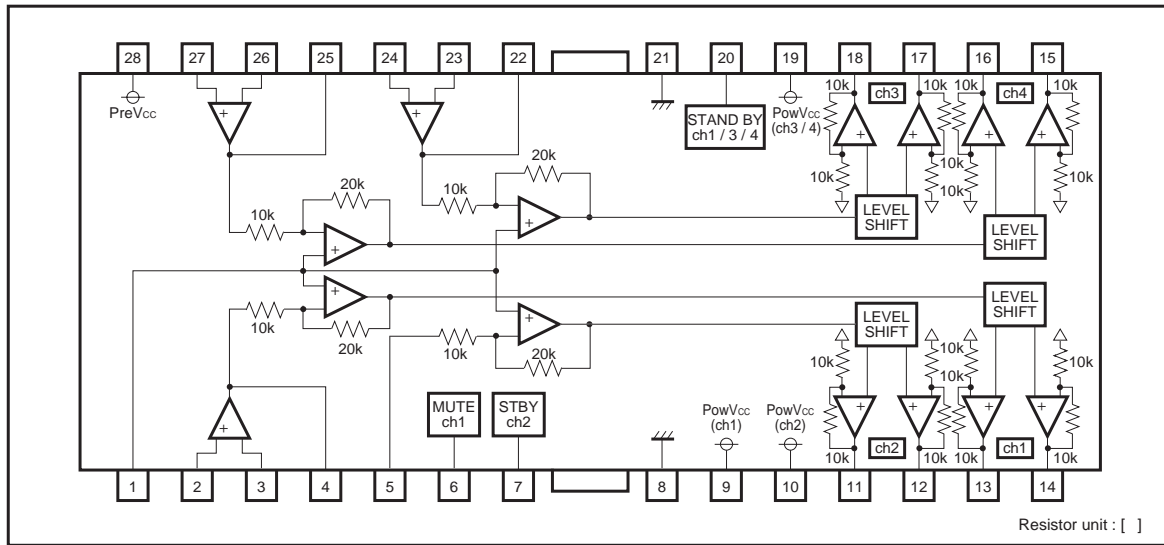


MGT188

PINNING

| SYMBOL | PIN | DESCRIPTION |
|------------------|------------|--|
| V _{SSA} | 1 | motor control ground supply |
| BIAS | 2 | Hall element bias |
| ROSC | 3 | external resistor for internal oscillator |
| REMF | 4 | external resistor for EMF regeneration |
| RLIM | 5 | external resistor for current limiting |
| FG | 6 | frequency generator output |
| EC | 7 | output current control pin |
| ECR | 8 | output current control reference voltage pin |
| i.c. | 9 | internally connected (leave open-circuit) |
| CP1 | 10 | booster capacitor connection 1 |
| CP2 | 11 | booster capacitor connection 2 |
| CAPY | 12 | booster output |
| V _{DDM} | 13 | motor supply voltage |
| W | 14 | motor terminal W |
| GND | 15 | ground supply |
| V _{DDM} | 16 | motor supply voltage |
| GND | 17 | ground supply |
| n.c. | 18 | not connected |
| V | 19 | motor terminal V |
| GND | 20 | ground supply |
| U | 21 | motor terminal U |
| V _{DDM} | 22 | motor supply voltage |
| START | 23 | start/stop control pin |
| V _{DD} | 24 | system supply voltage |
| UP | 25 | positive Hall input U |
| UN | 26 | negative Hall input U |
| VP | 27 | positive Hall input V |
| VN | 28 | negative Hall input V |
| WP | 29 | positive Hall input W |
| WN | 30 | negative Hall input W |
| i.c. | 31 | internally connected (leave open-circuit) |
| COSC | 32 | external capacitor for internal oscillator |

**IC7408,7409 BA5995: Servo Board, 4-channel BTL driver
IC actuator and motor drive**



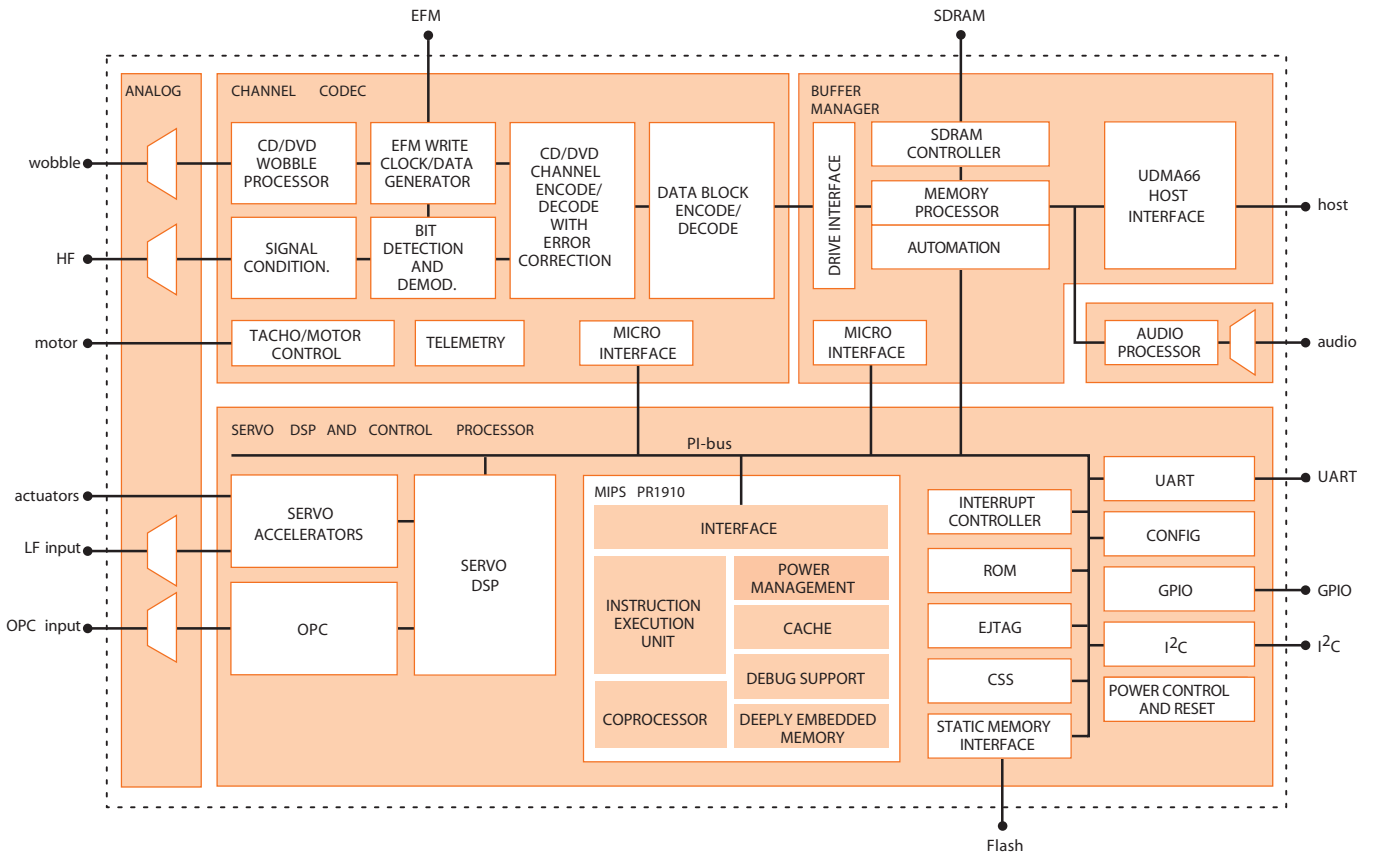
| Pin No. | Pin name | Function |
|---------|-----------|------------------------------------|
| 1 | BIAS IN | Input for bias-amplifier |
| 2 | OPIN1 (+) | Non inverting input for CH1 OP-AMP |
| 3 | OPIN1 () | Inverting input for CH1 OP-AMP |
| 4 | OPOUT1 | Output for CH1 OP-AMP |
| 5 | IN2 | Input for CH2 |
| 6 | MUTE | Input for CH1 mute control |
| 7 | STBY2 | Input for CH2 stand by control |
| 8 | GND | Substrate ground |
| 9 | PowVcc1 | Vcc for CH1 power block |
| 10 | PowVcc2 | Vcc for CH2 power block |
| 11 | Vo2 () | Inverted output of CH2 |
| 12 | Vo2 (+) | Non inverted output of CH2 |
| 13 | Vo1 () | Inverted output of CH1 |
| 14 | Vo1 (+) | Non inverted output of CH1 |

| Pin No. | Pin name | Function |
|---------|-----------|------------------------------------|
| 15 | Vo4 (+) | Non inverted output of CH4 |
| 16 | Vo4 () | Inverted output of CH4 |
| 17 | Vo3 (+) | Non inverted output of CH3 |
| 18 | Vo3 () | Inverted output of CH3 |
| 19 | PowVcc3 | Vcc for CH3/4 power block |
| 20 | STBY1 | Input for CH1/3/4 stand by control |
| 21 | GND | Substrate ground |
| 22 | OPOUT3 | Output for CH3 OP-AMP |
| 23 | OPIN3 () | Inverting input for CH3 OP-AMP |
| 24 | OPIN3 (+) | Non inverting input for CH3 OP-AMP |
| 25 | OPOUT4 | Output for CH4 OP-AMP |
| 26 | OPIN4 () | Inverting input for CH4 OP-AMP |
| 27 | OPIN4 (+) | Non inverting input for CH4 OP-AMP |
| 28 | PreVcc | Vcc for pre block |

Note) Symbol of + and (output of drivers) means polarity to input pin.
(For example if voltage of pin4 high, pin14 is high.)

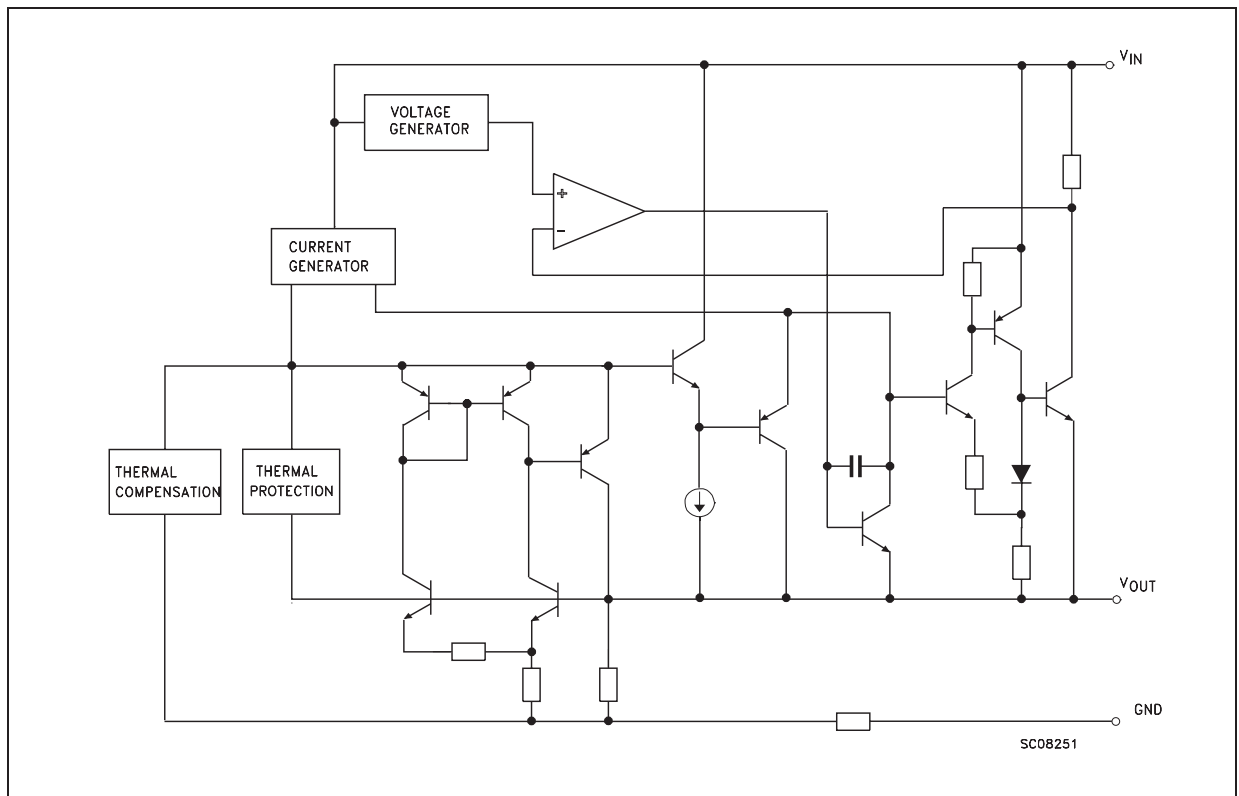
IC7500, PNX7850: Servo Board, Channel Codec/Buffer Manager/Servo Processor and Controller

Nexperia PNX7850 conceptual block diagram



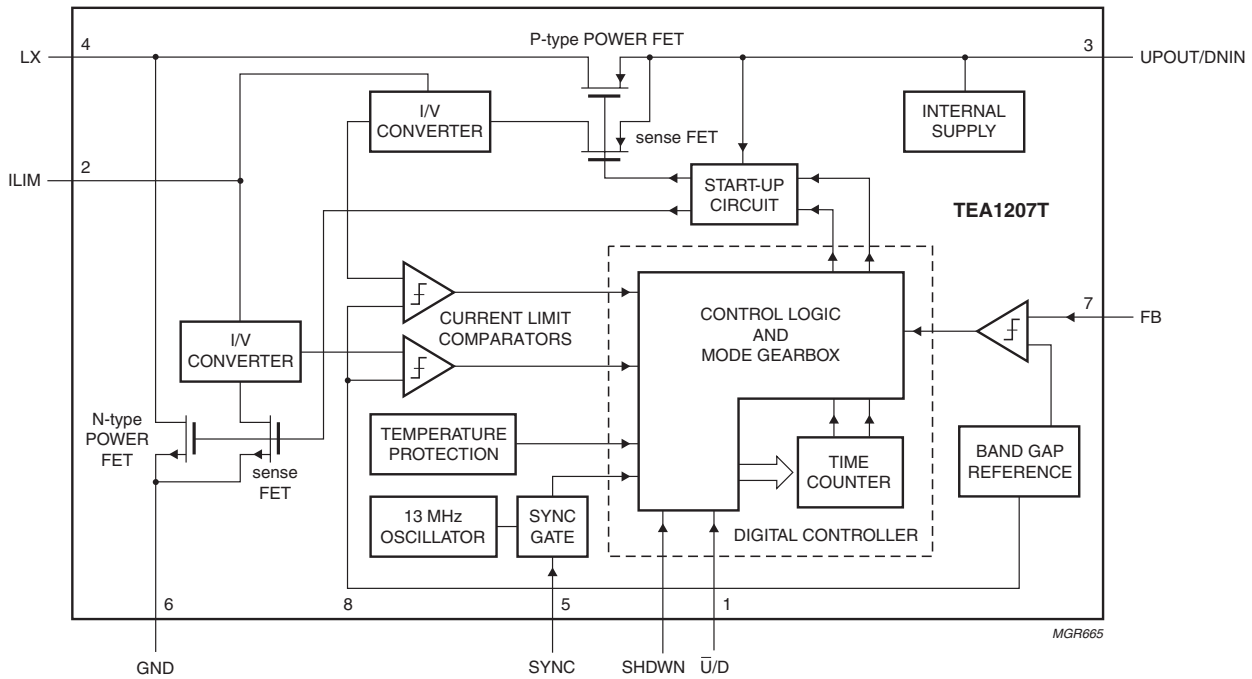
IC7603, LD1117: Servo Board, Voltage Regulator

BLOCK DIAGRAM

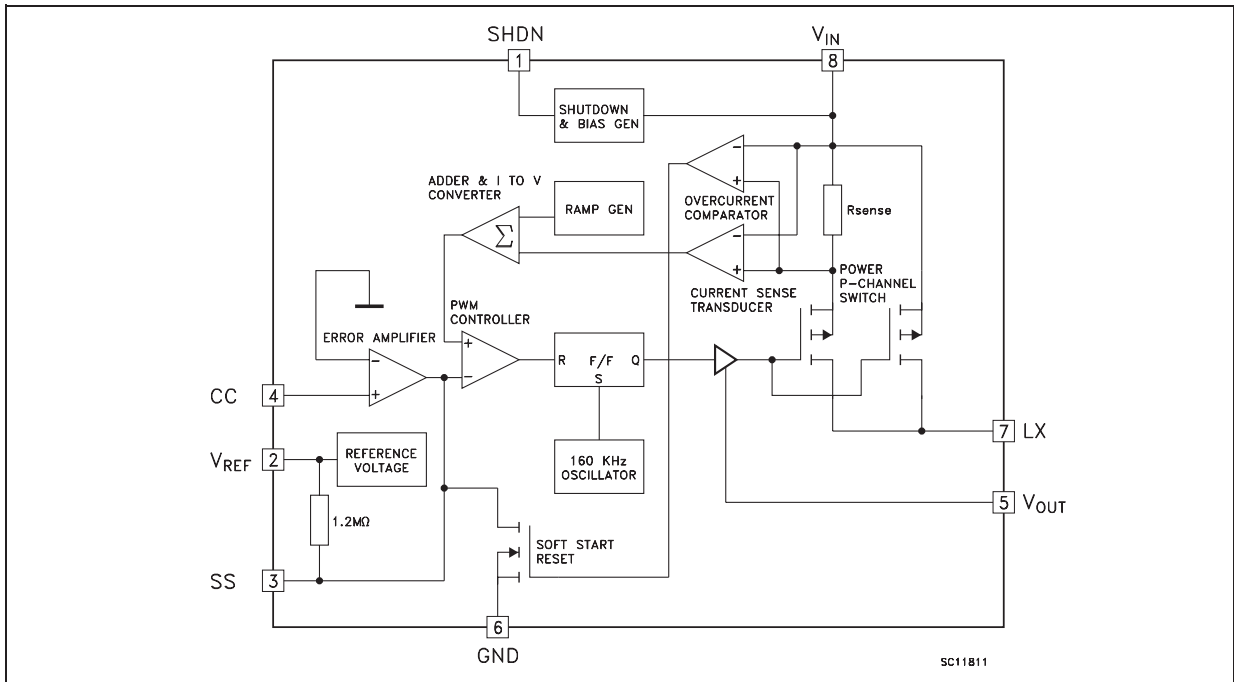


IC7604, TEA1207: Servo Board, DC/DC Converter

Block diagram

**PINNING**

| SYMBOL | PIN | DESCRIPTION |
|-------------|-----|---|
| \bar{U}/D | 1 | up-or-down mode selection input; active LOW for up mode |
| ILIM | 2 | current limiting resistor connection |
| UPOUT/DNIN | 3 | output voltage in up mode; input voltage in down mode |
| LX | 4 | inductor connection |
| SYNC | 5 | synchronization clock input |
| GND | 6 | ground |
| FB | 7 | feedback input |
| SHDWN | 8 | shut-down input |

IC7605, ST735: Servo Board, -5V Inverting PWM Regulator**SCHEMATIC DIAGRAM****PIN DESCRIPTION**

| Pin N° | Symbol | Name and Function |
|--------|-----------|--|
| 1 | SHDN | SHUT-DOWN Control (V_{CC} =ON GND=Shutdown) |
| 2 | V_{REF} | Reference Output Voltage |
| 3 | SS | Soft Start |
| 4 | CC | Compensation Input |
| 5 | V_{OUT} | Negative Output Voltage |
| 6 | GND | Ground |
| 7 | LX | Switch Output |
| 8 | V_{IN} | Positive Supply - Voltage Input |

IC7606, L5970: Servo Board, Step Down Switching Regulator**PINS FUNCTION**

| N. | Name | Description |
|----|-----------|--|
| 1 | OUT | Regulator Output. |
| 2 | SYNC | Master/slave synchronization. |
| 3 | INH | A logical signal (active high) disables the device. If INH not used the pin must be grounded. When it is open an internal pull-up disable the device. |
| 4 | COMP | E/A output for frequency compensation. |
| 5 | FB | Feedback input. Connecting directly to this pin results in an output voltage of 1.23V. An external resistive divider is required for higher output voltages. |
| 6 | V_{REF} | 3.3V V_{REF} . No cap is requested for stability. |
| 7 | GND | Ground. |
| 8 | V_{CC} | Unregulated DC input voltage. |

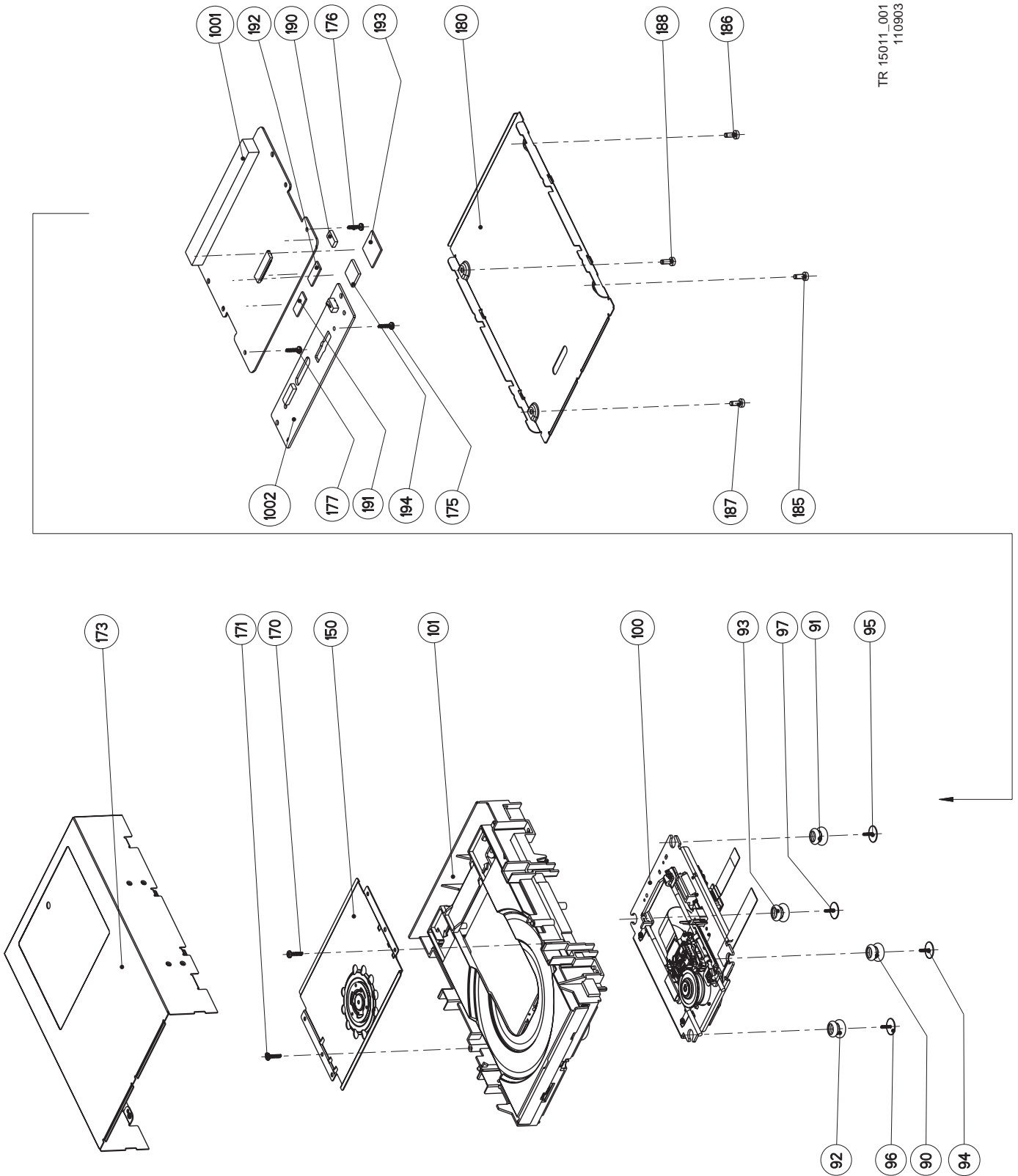
9.9 Abbreviation list

| | | | |
|---------------|---|----------|---|
| ADC..... | Analogue to Digital Converter | uP..... | Microprocessor |
| ADIP..... | Address In Pre-groove | VCD..... | Video CD |
| AGC..... | Automatic Gain Control | Y/C..... | Luminance (Y) and Chrominance (C) signal |
| CD..... | Compact Disc | YUV..... | Component video |
| CLV..... | Constant Linear Velocity | | |
| DROPPI..... | Dvd Rewritable Opu Pre-Processor IC | | |
| AM..... | Amplitude Modulation | | |
| BE..... | Basic Engine | | |
| ComPair..... | Computer aided rePair | | |
| CD-DA..... | CD Digital Audio | | |
| CS..... | Chip Select | | |
| DAC..... | Digital to Analogue Converter | | |
| DAIO..... | Digital Audio Input Output | | |
| DENC..... | Digital Encoder | | |
| DFU..... | Direction For Use: description for the end user | | |
| DNR..... | Dynamic Noise Reduction | | |
| DRAM..... | Dynamic RAM | | |
| DSD..... | Direct Stream Digital | | |
| DSP..... | Digital Signal Processing | | |
| DVD..... | Digital Versatile Disc | | |
| EEPROM..... | Electrical Erasable Programmable ROM | | |
| EFM..... | Eight to Fourteen bit Modulation | | |
| FDS..... | Full Diagnostic Software | | |
| HF..... | High Frequency | | |
| I2C..... | Integrated Ic bus (signals at 5V level) | | |
| I2S..... | Integrated Ic Sound bus (signals at 3.3V level) | | |
| IC..... | Integrated Circuit | | |
| IF..... | Intermediate Frequency | | |
| IRQ..... | Interrupt ReQuest | | |
| LADIC..... | LAser Driver IC | | |
| LLD..... | Loss Less Decoder | | |
| LPCM..... | Linear Pulse Code Modulation | | |
| LRCLK..... | Left/Right CLock | | |
| MACE..... | Mini All Cd Engine | | |
| MPEG..... | Motion Pictures Experts Group | | |
| NC..... | Not Connected | | |
| NVM..... | Non Volatile Memory: IC containing DVD related data e.g. alignments | | |
| OPC..... | Optimum Power Calibration | | |
| OPU..... | Optical Pickup Unit | | |
| PCB..... | Printed Circuit Board (see PWB) | | |
| PCS..... | Position Control Sledge | | |
| PLL..... | Phase Locked Loop | | |
| PCM..... | Pulse Code Modulation | | |
| PCM_CLK..... | Audio system clock for DAC | | |
| PCM_OUTx..... | Audio serial output data | | |
| PSU..... | Power Supply Unit | | |
| PWB..... | Printed Wiring Board (see PCB) | | |
| RAM..... | Random Access Memory | | |
| RGB..... | Red, Green and Blue colour space | | |
| ROM..... | Read Only Memory | | |
| RF..... | Radio Frequency | | |
| S2B..... | Serial to Basic engine, communication bus between host- and servo processor | | |
| SCL..... | Serial Clock I2C | | |
| SCLK..... | Audio serial bit clock | | |
| SDA..... | Serial Data I2C | | |
| SDRAM..... | Synchronous DRAM | | |
| SMC..... | Surface Mounted Components | | |
| S/PDIF..... | Sony Philips Digital InterFace | | |
| SPIDRE..... | Signal Processing Ic for Dvd R Ewritable | | |
| SRAM..... | Static Random Access Memory | | |
| STBY..... | STandBY | | |
| SVCD..... | Super Video CD | | |
| SW..... | SoftWare | | |
| THD..... | Total Harmonic Distortion | | |
| TTL..... | Transistor Transistor Logic (5V logic) | | |

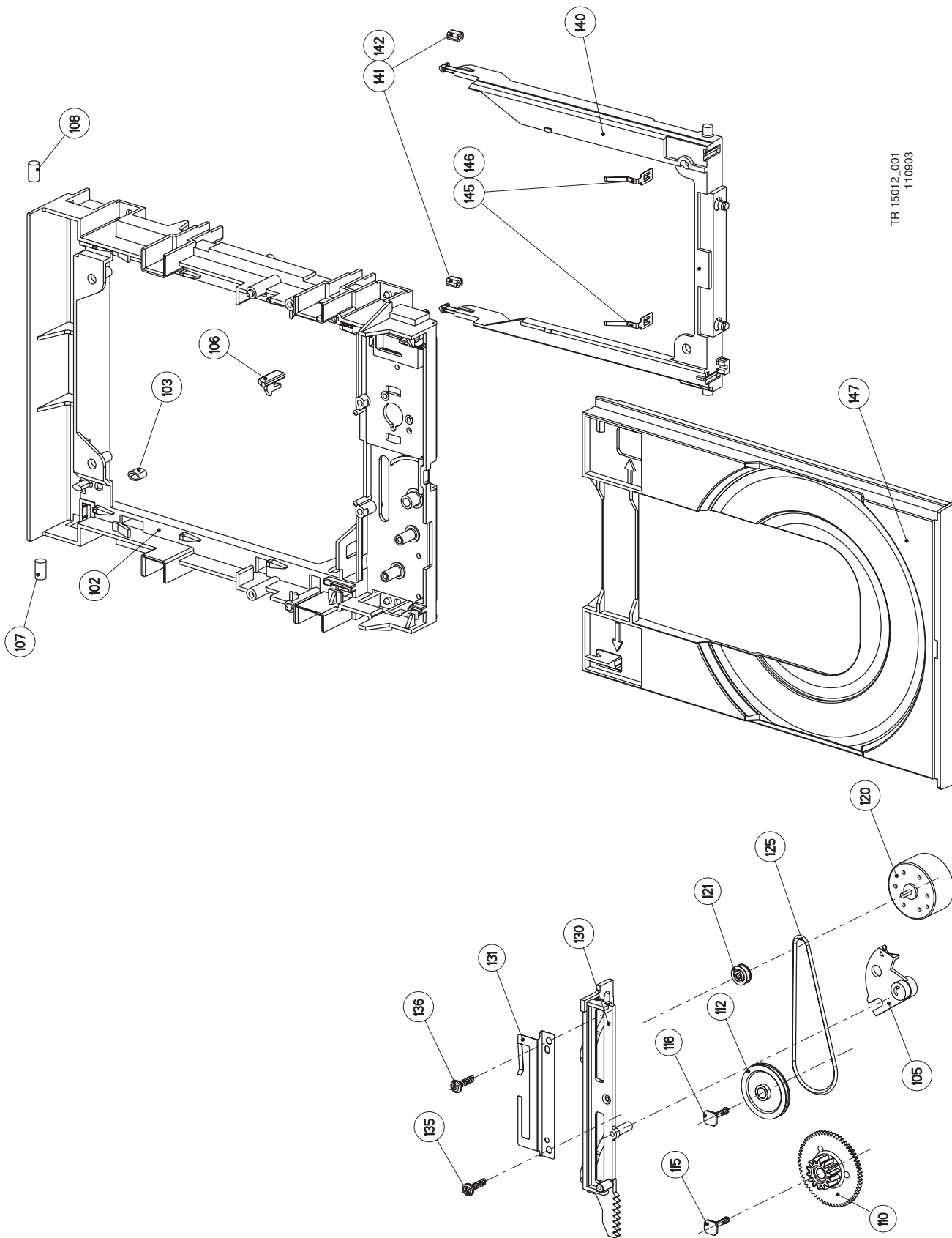
10. Spare Parts List

10.1 Exploded Views

Basic Engine

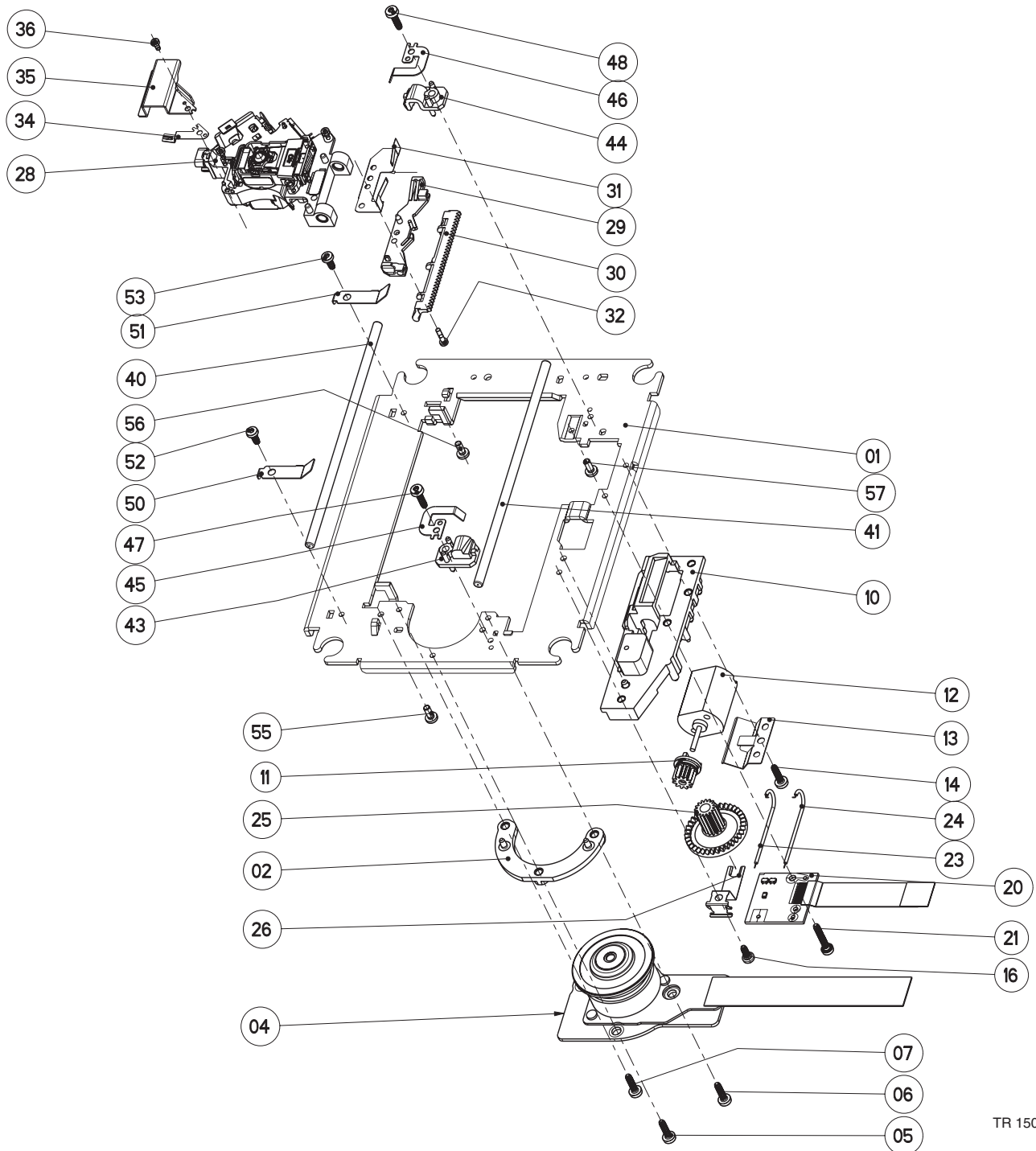


Loader



TR 15012_001
110903

DVD-M



Basic Engine VAD8031

Various

| | | |
|-------|----------------|---------------------------------|
| | 7104 099 91731 | LVP 12.01 MARGINAL DISC |
| | 7104 099 96581 | CD-RW LOW REFLECTION AUDIO DISC |
| 10-12 | 3104 148 01500 | SLEDGE MOTOR ASSY |
| 0090 | 3104 144 03901 | SUSPENSION |
| 0091 | 3104 144 03901 | SUSPENSION |
| 0092 | 3104 144 03901 | SUSPENSION |
| 0093 | 3104 144 03901 | SUSPENSION |
| 0094 | 3104 140 40622 | DVDM MOUNTING SCREW |
| 0095 | 3104 140 40622 | DVDM MOUNTING SCREW |
| 0096 | 3104 140 40622 | DVDM MOUNTING SCREW |
| 0097 | 3104 140 40622 | DVDM MOUNTING SCREW |
| 0100 | 9305 022 83001 | DVDM 8031/01 (AV3) |
| 0101 | 3122 487 90041 | LOADER ASSY |
| 0125 | 3104 144 10121 | TRAY MOTOR BELT |
| 0147 | 3104 144 04272 | TRAY |
| 0150 | 3122 487 90021 | CLAMPER PLATE |
| 1002 | 3104 128 09061 | LOADER TRAY MOTOR ASSY |
| 8000 | 3104 157 12231 | FLEX CONNECTION WIRES (ALL) |

PCB Assy 4343 Data 3

Various

| | | |
|------|----------------|-------------------|
| 1100 | 2422 025 17821 | CON H 45P F 0.50 |
| 1302 | 2422 543 01025 | Crystal 16.93 MHz |
| 1400 | 2422 025 17361 | CON BM H 9P |
| 1401 | 2422 025 17264 | CON BM H 11P |
| 1600 | 2422 033 00396 | SOC COMBI H 56P |
| 1702 | 2422 025 17359 | CON BM H 15P |

—||—

| | | |
|------|----------------|-----------------------|
| 2100 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2101 | 4822 126 13883 | 220pF 5% 50V |
| 2102 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2103 | 2020 552 94427 | 100pF 5% 50V 0603 |
| 2104 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2105 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2106 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2107 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2108 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2206 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2207 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2209 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2210 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2211 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2212 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2213 | 2238 786 56642 | 27nF 16V 0603 X7R 10% |
| 2214 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2215 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2217 | 3198 017 34730 | 47nF 16V 0603 |
| 2218 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2219 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2220 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2221 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2222 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2223 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2300 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2301 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2302 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2303 | 4822 122 33752 | 15pF 5% 50V |
| 2304 | 4822 122 33752 | 15pF 5% 50V |
| 2305 | 2238 916 15641 | 22nF 10% 25V 0603 |
| 2306 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2307 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2310 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2311 | 5322 126 11578 | 1nF 10% 50V 0603 |
| 2312 | 4822 122 33752 | 15pF 5% 50V |
| 2400 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2401 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2403 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2405 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2406 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2407 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2409 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2411 | 2020 552 94427 | 100pF 5% 50V 0603 |
| 2412 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2413 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2414 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2415 | 2238 916 15641 | 22nF 10% 25V 0603 |
| 2417 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2418 | 4822 126 14238 | 2.2nF 50V 0603 |
| 2419 | 4822 126 14238 | 2.2nF 50V 0603 |

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| 2420 | 4822 126 14238 | 2.2nF 50V 0603 |
| 2421 | 4822 126 13193 | 4.7nF 10% 63V |
| 2426 | 4822 126 14043 | 1µF 20% 16V |
| 2427 | 2238 586 15628 | 2.7nF 10% 50V 0603 |
| 2430 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2431 | 4822 124 23002 | 10µF 20% 16V |
| 2432 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2433 | 2022 552 05636 | 10µF 1210 X5R 16V 10% |
| 2434 | 4822 126 14238 | 2.2nF 50V 0603 |
| 2435 | 4822 126 14238 | 2.2nF 50V 0603 |
| 2436 | 4822 126 14238 | 2.2nF 50V 0603 |
| 2438 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2440 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2441 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2442 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2443 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2444 | 2022 552 05616 | 4.7µF 6.3V 0805 X5R |
| 2445 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2500 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2501 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2502 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2503 | 4822 126 13879 | 220nF 20% 16V |
| 2504 | 5322 126 11578 | 1nF 10% 50V 0603 |
| 2505 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2506 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2507 | 5322 126 11582 | 6.8nF 10% 63V |
| 2509 | 4822 126 13881 | 470pF 5% 50V |
| 2511 | 4822 126 13881 | 470pF 5% 50V |
| 2512 | 4822 126 13881 | 470pF 5% 50V |
| 2514 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2515 | 4822 124 23002 | 10µF 20% 16V |
| 2516 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2517 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2518 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2519 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2520 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2521 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2522 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2523 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2524 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2525 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2526 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2527 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2528 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2529 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2530 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2531 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2533 | 4822 124 23002 | 10µF 20% 16V |
| 2534 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2536 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2538 | 4822 124 23002 | 10µF 20% 16V |
| 2540 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2540 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2551 | 4822 122 33753 | 150pF 5% 50V |
| 2552 | 4822 122 33753 | 150pF 5% 50V |
| 2561 | 3198 017 34730 | 47nF 16V 0603 |
| 2562 | 3198 017 34730 | 47nF 16V 0603 |
| 2565 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2566 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2567 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2568 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2569 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2570 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2571 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2577 | 5322 126 11582 | 6.8nF 10% 63V |
| 2578 | 4822 126 14549 | 33nF 16V 0603 |
| 2579 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2580 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2581 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2602 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2603 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2605 | 4822 122 33741 | 10pF 10% 50V |
| 2607 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2608 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2610 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2611 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2612 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2615 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2616 | 4822 124 11131 | 47UF 6.3V |
| 2617 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2618 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2621 | 4822 124 11131 | 47UF 6.3V |
| 2622 | 4822 124 11131 | 47UF 6.3V |
| 2623 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2624 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2625 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2626 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2650 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2651 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2652 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2653 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2654 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2656 | 2020 552 96637 | 10µF 6.3V 0805 X5R |
| 2657 | 3198 017 31530 | 15nF 20% 50V 0603 |
| 2658 | 4822 122 33753 | 150pF 5% 50V |
| 2659 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2660 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2661 | 2238 586 59812 | 100nF 20-80% 50V 0603 |
| 2662 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2663 | 4822 126 13883 | 220pF 5% 50V |
| 2664 | 2238 916 15641 | 22nF 10% 25V 0603 |
| 2665 | 2022 552 05635 | 22µF 16V X5R 10% |
| 2700 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2701 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2702 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2703 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2704 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2705 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2706 | 5322 126 11583 | 10nF 10% 50V 0603 |
| 2707 | 5322 126 11583 | 10nF 10% 50V 0603 |
| —W— | | |
| 3100 | 4822 117 13501 | 82Ω 5% 0.62W 0603 |
| 3101 | 4822 117 13501 | 82Ω 5% 0.62W 0603 |
| 3103 | 4822 051 30102 | 1kΩ 5% 0.062W |
| 3104 | 4822 051 30101 | 100Ω 5% 0.062W |
| 3105 | 4822 051 30102 | 1kΩ 5% 0.062W |
| 3106 | 4822 051 30102 | 1kΩ 5% 0.062W |
| 3107 | 4822 051 30102 | 1kΩ 5% 0.062W |
| 3110 | 4822 051 30103 | 10kΩ 5% 0.062W |
| 3111 | 4822 051 30103 | 10kΩ 5% 0.062W |
| 3112 | 4822 051 30102 | 1kΩ 5% 0.062W |
| 3113 | 4822 051 30102 | 1kΩ 5% 0.062W |
| 3114 | 4822 117 12968 | 820Ω 5% 0.62W |
| 3115 | 4822 051 30332 | 3.3kΩ 5% 0.062W |
| 3116 | 4822 051 30152 | 1.5kΩ 5% 0.062W |
| 3117 | 4822 051 30221 | 220Ω 5% 0.062W |
| 3118 | 4822 051 30102 | 1kΩ 5% 0.062W |
| 3200 | 4822 051 30101 | 100Ω 5% 0.062W |
| 3201 | 4822 051 30101 | 100Ω 5% 0.062W |
| 3203 | 4822 051 30103 | 10kΩ 5% 0.062W |
| 3205 | 5322 117 13029 | 47kΩ 1% 0.063W 0603 |
| 3206 | 5322 117 13029 | 47kΩ 1% 0.063W 0603 |
| 3207 | 4822 051 30103 | 10kΩ 5% 0.062W |
| 3208 | 4822 051 30103 | 10kΩ 5% 0.062W |
| 3209 | 4822 117 12903 | 1.8kΩ 1% 0.063W 0603 |
| 3210 | 4822 117 12903 | 1.8kΩ 1% 0.063W 0603 |
| 3211 | 4822 117 12903 | 1.8kΩ 1% 0.063W 0603 |
| 3212 | 4822 117 12903 | 1.8kΩ 1% 0.063W 0603 |
| 3213 | 4822 051 30183 | 18kΩ 5% 0.062W |
| 3214 | 4822 051 30273 | 27kΩ 5% 0.062W |
| 3217 | 4822 051 30333 | 33kΩ 5% 0.062W |
| 3301 | 4822 051 30103 | 10kΩ 5% 0.062W |
| 3302 | 4822 117 12917 | 1Ω 5% 0.062W 0603 |
| 3303 | 4822 051 30151 | 150Ω 5% 0.062W |

